



Timing the time of concentration: light on a paradox

Journal:	<i>Hydrological Sciences Journal</i>
Manuscript ID	HSJ-2017-0384.R1
Manuscript Type:	Original Article
Date Submitted by the Author:	24-Jan-2018
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Keywords:	varying time of concentration, kinematic method, rational method, excess rainfall, regionalisation, GIS

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Timing the time of concentration: light on a paradox

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Abstract

From the origins of hydrology, the time of concentration, t_c , has been conventionally tackled as constant quantity. However, theoretical proof and empirical evidence imply that t_c exhibits significant variability against rainfall, making its definition and estimation a hydrological paradox. Adopting the assumptions of the Rational method and the kinematic approach, an effective procedure in a GIS environment for estimating the travel time across a catchment's longest flow path is provided. By applying it in 30 Mediterranean basins, it is illustrated that t_c is a negative power function of excess rainfall intensity. Regional formulas are established to infer its multiplier (unit time of concentration) and exponent from abstract geomorphological information, which are validated against observed data and theoretical literature outcomes. Besides offering a fast and easy solution to the paradox, we highlight the necessity for implementing the varying t_c concept within hydrological modelling, signalling a major shift from current engineering practices.

Keywords: varying time of concentration; kinematic method; longest flow path; Rational method; excess rainfall; unit time of concentration; calibration; regionalisation; GIS; travel time

1. Introduction

In hydrological sciences, the time of concentration, t_c , plays a crucial role as a defining factor of the catchment's response to rainfall excess over its surface.

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3 Particularly, in the context of everyday engineering applications, t_c has been widely
4 used as input to common hydrological design tools, such as the Rational method and the
5 unit hydrograph theory. However, due to the numerous definitions and estimation
6 procedures that are available in the literature (McCuen 2009; Gericke and Smithers
7 2014), resulting in substantially different design values of t_c , the latter remains one of
8 the most ambiguous and uncertain concepts of modern hydrology, or, quoting Grimaldi
9 *et al.* (2012) a *paradox*.

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18 Typically, t_c is considered as the longest travel time that runoff takes to travel
19 from the hydraulically most distant point in the watershed to the outlet (NRCS 2010).
20 Obviously, this is a theoretical interpretation, which raises significant questions about
21 the determination of t_c . In general, this travel time is applied only to surface runoff
22 (produced by the so-called excess or effective rainfall), although excess rainfall is not
23 the sole and not even the most important component of a flood hydrograph. In addition,
24 the hydraulically most distant point, defining the longest travel time to the watershed
25 outlet, does not necessarily coincide with the longest flow distance, and thus cannot be
26 always identified a priori (i.e., on the basis of river network geometry). Finally, the
27 quantity of runoff, which is essential information for determining the travel time, is
28 missing from the classical definition of t_c . We highlight that in many hydrological
29 textbooks the (poetic) expression “a drop of rainwater” is also used instead of the term
30 “surface runoff”, maybe in an attempt to associate the time of concentration with very
31 small flood events. It is interesting to remark that from a hydraulic perspective, a single
32 drop of rainwater would actually require infinite time to reach the outlet point of a
33 watershed, which is an obvious paradox.

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53 The estimation of t_c on the basis of observed data is also subject to major
54 uncertainties. Direct experimental observations of the travel time, based on radioactive
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3 and chemical tracers, are very rare and, nevertheless, have limited practical value
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5 (Grimaldi *et al.* 2012). On the other hand, indirect estimations, based on hydrograph
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7 analysis, requires arbitrary assumptions, including some kind of modelling (e.g., for the
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9 extraction of effective from gross rainfall), while a strict definition for determining the
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11 essential time quantities does not exist. McCuen (2009) reports six different
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13 computational definitions for the time of concentration through rainfall-runoff
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15 observations, in which t_c is also confused with other time-related concepts, such as the
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17 lag time and the time to peak, thus leading to significant inconsistencies (cf. Gericke
18
19 and Smithers 2014, also providing a comprehensive literature review on the existing t_c
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21 formulas).
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24 In fact, the major inconsistency regarding the definition and estimation of t_c is
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26 associated with its usual treatment as a constant parameter of the basin rather than a
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28 hydraulic variable, especially in the context of flood design recipes. Efstratiadis *et al.*
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30 (2014) are very critical about this consideration, since both empirical and theoretical
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32 evidence point to the contrary. However, most of the traditional empirical formulas
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34 (e.g., Giandotti, Kirpich, SCS) associating t_c with lumped geomorphological
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36 characteristics of the catchment (e.g., area, slope, river length), ignore the obvious
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38 dependence of the velocity and thus the travel time on runoff that is generated over the
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40 catchment and is next propagated along the river network. The evident impact of this
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42 clear paradox error is the underestimation of flood flows, particularly for extreme flood
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44 events that produce significant surface runoff, thus resulting in significantly increased
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46 flow velocities and, consequently, greatly decreased travel times against usual events. It
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48 is remarked that a flow-dependent time of concentration is a significant facet of
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50 nonlinearity within the rainfall-runoff transformation, and may explain the struggle of
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52 common hydrological models in reproducing the observed flow maxima.
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3 Interestingly, the correct hypothesis of a varying t_c is not new. From the early
4 steps of applied hydrology, several researchers have detected the inherently dynamic
5 behaviour of t_c and provided empirical formulas that account for an explanatory
6 variable, usually expressed in terms of rainfall intensity (gross or effective). A synoptic
7 description of such methods is given in the next section. Most are based on simplified
8 hydraulic approaches (e.g., kinematic wave), while others are empirically derived on the
9 basis of field data. Recently, the problem is revisited through the use of GIS tools,
10 which allow the employment of a flow velocity method at the grid scale. By definition,
11 GIS-based approaches explicitly account for the dependence of t_c on flow, since in order
12 to implement a flow velocity procedure to estimate t_c it is necessary to assign a runoff
13 depth to each cell. The advantages and shortcomings of such approaches are also
14 discussed below.

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Accounting for the fundamental assumption of a varying time of concentration, the objectives of this research are twofold. First, we provide an analytical procedure to facilitate the estimation of the travel time and peak discharge for a given rainfall excess, which is considered uniformly distributed over the catchment. In this context, we implement a simplified velocity approach in a GIS environment, inspired by the hydraulic design for urban sewer networks. The method is implemented across the longest flow path of the catchment, which is divided into a limited number of sub-reaches. Using easily-retrieved geographical data from a large number of basins of diverse sizes and shapes in Italy, Greece and Cyprus, the travel time for different runoff intensities is calculated and a power-type relationship among them is fitted. Taking advantage of these data, we establish regional formulas for the two coefficients, i.e. the scaling factor (referred to as unit time of concentration) and the exponent, which are expressed as functions of key geomorphological characteristics of the catchment and the

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3 main watercourse. Comparisons with literature data indicate that the proposed
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5 regionalisation approach provides realistic estimations of the varying behaviour of the
6
7 time of concentration, and can be easily used as alternative to the analytical approach.

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9 In the discussion section, we also provide recommendations for incorporating the
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11 paradigm of the varying time of concentration into everyday engineering practice.
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14 15 **2. Brief review of existing approaches for associating t_c with rainfall intensity**

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17 Table 1 contains a summary of the empirical formulas developed to date, which assign
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19 either the gross or the effective (excess) rainfall intensity to a time of concentration. To
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21 our knowledge, the first attempt is attributed to Izzard (1947). Based on overland flow
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23 experiments, Izzard (1947) showed that rainfall intensity influences t_c and provided an
24
25 experimental formula of t_c that accounted for both the catchment's geomorphology and
26
27 the rainfall excess intensity; however, its application is only suitable for roadway and
28
29 turf surfaces. Later, the United States Army Corps of Engineers conducted experiments
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31 on artificial concrete surfaces and obtained a relationship to estimate t_c based on excess
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33 rainfall intensity relationship. Similarly, Morgali and Linsley (1965) derived a
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35 relationship between t_c and excess rainfall intensity which was derived from Manning's
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37 formula for overland flow and a kinematic wave approximation, with the overland flow
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39 path length and surface slope as parameters, but is limited to paved areas.
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45 Rao and Delleur (1974) asserted that the lag time and, hence, the time of concentration,
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47 are not unique watershed characteristics but are varying from storm to storm. They
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49 attributed this variation to several reasons, including the amount, duration and intensity
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51 of rainfall, vegetative growth stage and available temporary storage. Singh (1976)
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53 derived mathematical expressions from the kinematic wave theory for the calculation of
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55 t_c and concluded that besides watershed characteristics, the temporal and spatial rainfall
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3 patterns are crucial for estimating t_c , underlining that the Kirpich's formula (Table 2) is
4 a special case of a very general expression that is valid under very limited conditions.
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6 Yu *et al.* (2000) developed power-law curves for peak runoff rate-lag time, by utilising
7
8 measurements of experiments conducted on different surfaces. The influence of the
9
10 temporal rainfall pattern has been also recently investigated by Kjeldsen *et al.* (2016),
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12 who studied observed hydrographs and confirmed that the response time of a catchment
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14 decreases with the increase of average rainfall intensity.
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18 Another semi-analytical relation for the t_c in a channel, as a function of intensity
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20 of excess rainfall intensity, length and slope of the longest watercourse and Manning's
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22 coefficient, was derived by Papadakis and Kazan (1987) who used data from 84 rural
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24 catchments smaller than 500 acres ($\sim 2.0 \text{ km}^2$), as well as very small experimental basin
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26 setups (375 area in total). Additionally, many other researchers (e.g., Askew 1970,
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28 Kadoya and Fukushima 1979, Aron *et al.* 1990, Loukas and Quick 1996) derived
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30 theoretical or empirical formulae to link key flood time characteristics with flood
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32 quantities. Some of the overland flow regional formulas were tested by Wong (2005),
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34 using two experimental concrete and grass bays of small dimensions and a rainfall
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36 simulator. He concluded that accounting for rainfall intensity is generally in agreement
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38 with the experimental data.
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42 As already mentioned, the large expansion of GIS tools during the last three
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44 decades allowed for the employment of the flow velocity method at a grid scale, thus
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46 providing a "physically" sounder approach, in which the velocities, and thus the time of
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48 concentration, are estimated cell by cell, for a given runoff depth. Saghafian *et al.*
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50 (2002) and Meyersohn (2016) demonstrated, using the isochrones method (the former in
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52 a small basin of 0.16 km^2 in West Africa and the latter in a basin of 282 km^2 in
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54 Northern California), that the time of concentration is indeed a power function of excess
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3 rainfall intensity. Grimaldi *et al.* (2012) calculated t_c for a number of observed rainfall-
4 runoff events in four small basins (<120 km²), by implementing the procedure of the
5 Natural Resources Conservation Service (Cronshey 1986). They concluded that t_c can
6 vary up to 500 %, and in most cases this variability is increased as the catchment area
7 increases. Moreover, they indicated that a power-type relationship can coarsely describe
8 the decrease of t_c against the increase of the peak discharge.
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15 Pavlovic and Moglen (2008) are quite critical about raster-based estimates, since
16 continuity of discharge and water depth is ignored. Additionally, they contemplated the
17 problems regarding over-discretisation, stating that when discretising in small segments
18 the sudden anomalies in slope change the flow regime and thus lead to a less
19 representative overall water depth. In fact, they have shown that decreasing the pixel
20 size, where the velocity calculation is performed, can even double the t_c . They
21 concluded that the use of relatively long channel sections should prevent this problem
22 and give more accurate travel time estimates. Saghafian *et al.* (2002) have also
23 acknowledged the issue, without, however, further addressing it.
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36 **3. Simplified velocity method for estimating t_c across the longest flow path**

37 **3.1 Overview and assumptions**

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40 The proposed methodology for estimating the time of concentration as function of
41 runoff intensity is based on a velocity approach, as employed within the hydraulic
42 design of urban sewer networks. According to conventional practice, the design flow is
43 estimated through the Rational method, where the time of concentration – an input
44 parameter of the critical rainfall intensity – is the sum of the inlet time and the flow time
45 in the upstream sewers connected to the outlet. The implementation of this method is
46 employed from upstream to downstream, thus at each section of storm sewer a peak
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3 discharge is assigned, by considering the total upstream area, the composite runoff
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5 coefficient, and the associated time of concentration. The peak discharge is updated
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7 from node to node, thus across each individual segment the flow is steady.
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10 In our context, we hypothesize a uniform runoff depth across the river basin,
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12 which is divided into sub-catchments, and solve the velocity method along its longest
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14 flow path. As shown in Fig. 1, two flow types are considered: (a) overland flow,
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16 occurring in the headwater (i.e. the most upstream sub-catchment) where the flow paths
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18 are not well defined; and (b) channel flow, which is propagated along the main
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20 watercourse comprised of sub-reaches. We remark that according to the standard NRCS
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22 approach (Cronshey 1986), overland runoff can be further divided into sheet flow and
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24 shallow concentrated flow; sheet flow occurs near the ridgeline and is developed over
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26 planes surfaces, for an arbitrary limited length of typically 100 feet (30 m), and later
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28 becomes shallow concentrated flow collected in swales, small rills and gullies (NRCS,
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30 2010). For simplicity, these two sub-types are merged, thus avoiding the introduction of
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32 many parameters in order to describe highly complex processes for a generally very
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34 small portion of the longest flow path.
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38 Within hydraulic calculations we consider steady uniform flow, which allows
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40 employing the Manning's equation to estimate the velocity of each individual
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42 component across the longest flow path, without accounting for routing phenomena
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44 (i.e., lagging and attenuation). Initially, we estimate the average velocity of the overland
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46 runoff, the associated travel time, next referred to as inlet time (for convenience, the
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48 notation of sewer network design is adopted) and the input peak discharge to the main
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50 stream. Next, we move downstream to estimate the travel time along each sub-reach
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52 (defined by two subsequent junctions), assuming rectangular sections, with known
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54 hydraulic properties (roughness, width, longitudinal slope). At each junction, the runoff
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3 intensity is updated, taking into account the travel time so far, and the associated peak
4 discharge, which is a function of the runoff intensity and the total upstream area. The
5 computational procedure is described in detail in the next sub-sections.
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9 Similarly to fully-distributed approaches, employing the time-area procedure
10 cell-by-cell, our methodology is also physically sound, yet it is much simpler and
11 parsimonious, due to the semi-distributed schematization. Key elements are the
12 delineation of the hydraulically most distant path, generally considered as the longest
13 flow path, and the assignment of control points (junctions) across it, receiving the runoff
14 generated by sub-basins (similarly to sewer network design practices, only nodal
15 inflows are allowed, thus all distributed runoff is concentrated to junctions). The rest of
16 the model inputs are easily determined. In particular, as shown in Fig. 2, we have
17 developed a semi-automatic GIS procedure for the delineation of the spatial modelling
18 components (sub-catchments, sub-reaches and junctions) and the estimation of their
19 geometrical properties (areas, lengths, slopes). In essence, this consists of common
20 spatial computations (coloured yellow) – including flow accumulation and direction, as
21 well as stream definition algorithms – and their outcomes (coloured in green), and has
22 as input the selected junctions and the study basin DEM and output the delineated basin
23 and the river segments of the longest flow path. The rest of inputs are associated with
24 hydraulic quantities (roughness coefficients, widths), which can be derived through
25 field surveys or approximately estimated by map information.
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47 ***3.2 Delineation and discretisation of the longest flow path***

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49 Our approach is based on a semi-distributed schematization of the catchment, initially
50 requiring the delineation of the river network and the determination of the longest flow
51 path. The river network is automatically extracted on the basis of a digital elevation
52 model (DEM), by adjusting the flow accumulation parameter (in our case studies, the
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2 threshold area criterion for stream definition was set equal to 1 km^2). From the detailed
3 network only the main stream is maintained, which is next discretised into sub-reaches,
4 by keeping the most important confluence junctions along it. Since inflows are only
5 allowed to junctions, the selection of confluences is an essential issue for a realistic
6 representation of the catchment response. In general, a relatively small number of
7 junctions describes quite satisfactory the propagation of flows across the main stream.
8 Occasionally, additional junctions have to be assigned in cases of significant changes of
9 the hydraulic characteristics of sub-reaches. For the selected junctions, the delineation
10 of upstream sub-catchments is implemented in the GIS environment.
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22 For a set of N junctions across the longest flow path, $N - 1$ travel times have to
23 be estimated. The most upstream junction, indexed $i = 0$, denotes the hydraulically most
24 distant point, while junction $i = 1$ denotes the transition point from overland to channel
25 flow. The identification of this transition is another critical issue of the methodology,
26 since in general overland velocity is much lower than channel velocity, thus overland
27 time is quite an important portion of the time of concentration. Although in the literature
28 several semi-empirical approaches are reported that use as sole input the DEM (e.g.,
29 Montgomery *et al.* 1988, Tarboton *et al.* 1991, Dietrich *et al.* 1993, Montgomery and
30 Foufoula-Georgiou 1993, McNamara *et al.* 2006), the problem is governed by
31 significant uncertainties and generally requires additional inspection, preferably
32 accounting for *in-situ* information.
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46 As already mentioned the longest flow path, as automatically extracted through
47 typical GIS calculations, does not necessarily coincide with the hydraulically remoter
48 path of the river basin. For this reason, we strongly recommend to carefully evaluate the
49 outcomes of this critical step of the methodology, in order to seek whether alternative
50 flow routes exist that pass, for example, from flat or mildly-sloped areas in the upstream
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parts of the basin. In such cases (which are not often), the longest flow path has to be manually changed, mainly based on common engineering sense. However, if it is not clear which of the alternative flow paths ends up to the hydraulically more distant point of the basin, it is preferably to repeat the computations across the different paths and finally select the one with the longest travel time.

3.3 Implementation of velocity method across the longest flow path

The algorithmic procedure, involving the application of the proposed velocity method along the longest flow path and the step-by-step estimation of the total travel time and peak discharge arriving to the current node, is very simple. For a given excess rainfall (runoff depth), P_e (m), which is considered uniformly distributed over the entire catchment, its transformation to peak discharge follows the Rational method concept, applied from upstream to downstream:

$$Q_i = \frac{P_e \sum_{j=0}^{i-1} A_j}{\sum_{j=0}^{i-1} t_j} \quad (1)$$

where Q_i ($\text{m}^3 \text{s}^{-1}$) is the inflow to the i -th junction ($i = 1, \dots, N-1$), A_j (m^2) is the area of the j -th sub-basin, and t_j (s) is the travel time through the j -th sub-reach.

By definition, t_0 represents the inlet time, which is associated with overland flow across the headwater sub-catchment, A_0 . In this area (and all hillslope areas, in general), the runoff processes and associated flow conditions are subject to great heterogeneity, undefined geometry and complex physical laws that render the analytical velocity calculation difficult with a lack of field data. For simplicity, t_0 is estimated through the shallow concentrated flow formula by the Soil Conservation Service (SCS; McCuen 1989):

$$t_0 = \frac{L_0}{V_0} = \frac{L_0}{k\sqrt{S_0}} \quad (2)$$

where V_0 is the overland velocity (m s^{-1}), k is a roughness coefficient (m s^{-1}) related to soil conditions, S_0 is the average slope of the overland flow (m/m), and L_0 (m) is the length of the overland flow, as measured from the most hydraulically distant point to the beginning of the well-formed main stream, i.e. from junction 0 to junction 1. The sole parameter of Eq. (1) is the roughness coefficient, for which McCuen (1989) and Haan *et al.* (1994) have proposed typical values, corresponding to different land cover types. In this context, parameter k can be determined from the available CORINE land cover maps, classifying land cover into diverse groups and, thus allowing the correspondence of them to a specific roughness coefficient value. We remark that the literature offers quite many expressions for hillslope velocity, requiring the specification of several hydraulic or empirical parameters. Grimaldi *et al.* (2010) have tested four typical formulas, concluding that the NRCS scheme (as well as the one proposed by Maidment *et al.* 1996), is suitable for defining the basin flow time, using just one parameter.

The rest of the time quantities, $t_1 \dots, t_{N-1}$ refer to travel times across the main stream. At each sub-reach i , downstream of junction i , the inflow Q_i is known by Eq. (1). In this respect, the channel velocity V_i (m s^{-1}) and associated travel time t_i (s) are explicitly obtained through the Manning equation, i.e.:

$$t_i = \frac{L_i}{V_i} = \frac{n_i L_i}{R_i^{2/3} J_i^{1/2}} \quad (3)$$

where L_i is the length of the sub-reach downstream of junction i , n_i is the roughness coefficient ($\text{s m}^{-1/3}$), R_i is the hydraulic radius (m), and J_i is the stream slope (m/m). For parsimony, rectangular cross-sections of known width b_i (m) are assumed, thus for the computation of the hydraulic radius and the velocity, we first solve the Manning equation for the water depth y_i (m), and the given inflow, i.e.:

$$Q_i - \frac{1}{n_i} \frac{J_i^{1/2} b_i^{5/3} y_i^{5/3}}{(b_i + 2y_i)^{2/3}} = 0 \quad (4)$$

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3 It is remarked that the above equation presupposes uniform flow conditions
4 along the sub-reach, and consequently constant section geometry. If the channel width
5 at the downstream junction, b_{i+1} , differs from the upstream one, b_i , the sub-reach is
6 divided into smaller computational segments, and the calculation of the hydraulic
7 variables across it (water depth, velocity, travel time) is made from the upstream
8 segment to the downstream one, by considering linear variation of the width and
9 constant inflow, Q_i .
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19 At the outlet junction, the time of concentration of the catchment, t_c is obtained,
20 by adding all upstream travel time values, t_i , while the outlet discharge is:
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$$23 \quad Q = P_e A / t_c \quad (5)$$

24
25 where A is the total catchment area. Finally, the quantity $i_e = P_e / t_c$ represents the
26 surface runoff rate, expressed in terms of effective rainfall intensity.
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30 In Fig. 3 we demonstrate the results of the algorithm across the mountainous
31 catchment of Nedontas river, Greece (114.8 km²), by setting a runoff depth of 10 mm.
32 The longest flow path is divided into six sub-reaches. At each sub-reach the flow
33 velocity and the corresponding travel time are estimated, while at each junction the
34 accumulated time and the corresponding discharge are estimated. For the
35 aforementioned runoff depth, the total travel time along the longest flow path, i.e. the
36 time of concentration of the basin, is 2.18 h, which equals to a runoff rate of
37 $10 / 2.18 = 4.6$ mm/h and an outlet discharge of $10 \times 114.8 / (2.18 \times 3.6) = 146$ m³/s. It
38 is interesting to remark that, in this specific case, about half of the travel time, i.e. 1.0
39 out of 2.2 h, is consumed for overland flow over the headwater sub-catchment, while
40 the channel flow is propagated much faster, as result of the steep slopes of the river
41 (7.4%, on average). Moreover, as expected, by moving downstream the flow velocity
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3 increases, since the decrease in depth overcompensates for the decrease in channel slope
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5 (Leopold and Maddock J. 1953).
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8 **3.4 Dealing with discretisation issues**

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11 As already acknowledged (e.g. Saghafian *et al.* 2002, Pavlovic and Moglen 2008), the
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13 calculation of t_c may be impacted by the discretisation issues that arise, which have
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15 studied more in pixel- and less in channel-based approaches. In particular, Pavlovic and
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17 Moglen (2008) investigated the effect of the number of segments to the estimated
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19 response time of a single study basin, concluding that the latter converges only after
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21 increasing substantially the number of segments. The appropriate number of segments
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23 will most probably differ across different basins. They also reported that by increasing
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25 the discretisation level does not necessarily increase the accuracy of the estimate.
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27 Similarly, Grimaldi *et al.* (2012) noticed that the time of concentration calculated by the
28
29 NRCS method tends to decrease when increasing the cell resolution.
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33 In our approach, the model domain discretisation mainly refers to the allocation
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35 of junctions across the longest flow path. As explained in Section 3.2, the junctions
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37 should be assigned to all major confluences of the main stream with secondary ones,
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39 while the user may also assign additional junctions, particularly in cases of significant
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41 changes of the channel characteristics, expressed in terms of width, slope and
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43 Manning's roughness coefficient. Nevertheless, since the junctions are unique inflow
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45 points across the longest flow path and lateral inflows are not allowed, the level of
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47 discretisation, and thus the essential number of junctions, strongly depends on the river
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49 network and catchment geometry. For this reason, we strongly recommend that
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51 junctions should be assigned by combining automatic (i.e., GIS-based) delineation
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53 procedures with visual inspection, in order to ensure a realistic representation of inflows
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55 across the main stream.
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3 In theory, the larger the number of inflow points (junctions), the more accurate
4 will be the estimation of the travel time. Preliminary analyses have indicated that a too
5 detailed discretisation has only a minor impact on model accuracy, in contrast to a very
6 coarse one, which affects the travel time estimations. In fact, by ignoring a significant
7 confluence, and thus accounting for the runoff of a relatively larger sub-basin, the travel
8 time will be underestimated, and this runoff will be erroneously assigned to a
9 downstream junction. On the other hand, the addition of a junction to a minor
10 confluence results in only a slight increase of the upstream area. Except for irregular
11 river network geometries, a minor increase of the drainage area is expected to be
12 counterbalanced by a similarly minor increase of the time of concentration so far, thus
13 only marginally affecting the peak flow estimations through Eq. (1). In Section 4.5, we
14 demonstrate the limited sensitivity of our procedure against different discretization
15 levels, using as example the largest of our study areas (Titarisios River, Thessaly).

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31 Another scaling issue involves the spatial resolution of the DEM, which is
32 associated with the mapping of the river network and the estimation of the geometrical
33 inputs of the model. Antoniadis (2016) has thoroughly investigated this topic by using as
34 an example the river basin of the Nedontas River, concluding that the time of
35 concentration is slightly underestimated as the DEM resolution becomes coarser.
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However, for relatively large runoff depths, the differences of t_c estimations become
negligible.

4. Application

4.1 Study basins

The proposed procedure for estimating the time of concentration, as well as the peak
discharge, using the Rational method assumptions, is applied to a sample of 30

1
2
3 Mediterranean basins from Italy, Greece and Cyprus (Fig. 4), with different
4
5 characteristics with respect to the catchment shape, extent, land cover and the river
6
7 network geometry. In particular, catchments of different sizes have been chosen, from
8
9 13.9 km² (Anavros Stream, Greece) to 1813 km² (Titarisios River, Greece), in order to
10
11 investigate the effect of the drainage area, since the majority of the already published
12
13 studies deal with small catchments. In Table 3 we summarize the key geomorphological
14
15 properties of the study areas, and we also provide estimations for the time of
16
17 concentration using the classical empirical formulas by Giandotti and Kirpich (Table 2),
18
19 which do not account for rainfall intensity. We remark that the two approaches result in
20
21 quite different estimations, the former being more representative for flood modelling of
22
23 Mediterranean catchments, as reported by Efstratiadis *et al.* (2014).
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28 **4.2 Input data**

29
30 For a given runoff depth, in order to run the GIS-based procedure it is essential to
31
32 delineate the study area into sub-catchments and sub-reaches, by assigning a number of
33
34 junctions along the longest flow path, and retrieve their geometrical and hydraulic data
35
36 needed for applying the governing equations (1), (2) and (3).
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40 For the delineation of the longest flow path, the allocation of junctions, the
41
42 discretisation of sub-catchments and sub-reaches, and the derivation of their geometrical
43
44 properties (areas, slopes, lengths) DEMs of varying resolutions are used, from 5×5 m up
45
46 to 30×30 m. As already mentioned, the DEM resolution plays a minor role on the
47
48 accuracy of t_c estimations. For the Italian basins, the DEMs were made available from
49
50 the Supreme Institute for Environmental Protection and Research (Istituto Superiore per
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52 la Protezione e la Ricerca Ambientale; [http://www.sinanet.isprambiente.it/it/sia-
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56 ispra/download-mais/dem20/view](http://www.sinanet.isprambiente.it/it/sia-
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54 ispra/download-mais/dem20/view)), while for the Greek basins, these data were
57
58 retrieved from the National Databank for Hydrological and Meteorological Information
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3 (<http://hydroscope.gr/>). Finally, for the two catchments of Cyprus spatial data from a
4 recent research programme were used, dealing with flood monitoring and modelling
5
6
7 (<http://deucalionproject.itia.ntua.gr/>).
8

9 The overland roughness coefficients, k , were determined on the basis of land
10 cover from the CORINE maps, following the recommendations by Haan *et al.* (1994)
11 and McCuen *et al.* (1998). Initially, maps of distributed roughness values were
12
13 produced, and then the average k over the headwater sub-catchments were calculated.
14
15
16

17 At each junction, a channel width and the Manning's roughness coefficient of
18 the downstream sub-reach were assigned, by combining several sources of information.
19
20 In particular, the widths, b , were determined either from field data (topographical
21 survey maps and satellite imagery) or, when possible, from the DEM. In some river
22 basins of Greece, otophotos from the pilot application of the Greek National Cadastre
23 were utilised. For the Italian basins in Lombardia and Emilia Romagna, topographic
24 relief maps were available online (geoportale.regione.emilia-romagna.it:
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ita.arpalombardia.it/ita/index.asp), along with additional information and maps (e.g.,
hydraulic structures, geology).

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In contrast to width, the Manning's coefficient across each sub-reach, which is an empirical parameter rather than a physical property, could not be estimated with high precision, since its value depends on various interacting factors such as friction, structure and texture of surface, vegetation density, obstacles, etc. Therefore, according to the mainstream engineering practice, we employed typical values of 0.020, 0.025 and 0.030 for concrete, gravel and earth channels, respectively, by approximately recognizing the bed material from satellite images. In the case of streams covered by dense vegetation, a Manning's coefficient equal to 0.04 was assigned.

The number of junctions assigned to each study basin, and the associated inputs, by means of averaged roughness coefficients and widths, are given in Table 4.

4.3 Results

At each study basin we employed six fixed runoff depths, equal to $P_e = 1, 5, 10, 25, 50$ and 100 mm, and estimated the corresponding time of concentration, t_c , the effective rainfall intensity, i_e , by dividing P_e with t_c , and the outlet discharge, Q , by further dividing with the catchment area, A . The results are summarized in Table 5, from which it can be easily recognised that the time of concentration is a recession function of the effective rainfall intensity (Fig. 5). In this respect, at each basin we fitted a power-type regression model to the six known pairs of i_e and t_c , i.e.:

$$t_c = t_0 i_e^{-\beta} \quad (6)$$

which yielded almost perfect predictions. In Table 4 the optimized values of parameters t_0 and β , as well as the R^2 values that range from 0.952 to 0.991 (0.979, on average) are provided. Therefore, Eq. (6) allows for explicitly estimating the time of concentration of these basins for any runoff intensity, without implementing the GIS procedure for this specific intensity. In general, one can employ the proposed procedure in a catchment of interest for a small yet representative sample of i_e values, and then fit a recession model to establish the analytical relationship of the catchment.

As shown in the examples of Fig. 5, Eq. (6) has an asymptotic behaviour, thus for extreme runoff intensities t_c converges to a minimum value, while for intensities tending to zero the time of concentration becomes infinite. Apparently, the application of the method for minimal runoff intensities, e.g., less than 0.1 mm/h, which result to very large values of t_c , is out of practical interest, given than the time of concentration

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3 concept is generally applicable within flood modelling, requiring the simulation of large
4
5 runoff events.
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8 **4.4 Theoretical interpretation of parameters t_0 and β**

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11 Eq. (6) is consistent with the studies reported in the literature, including theoretical and
12
13 experimental relationships reported (*cf.* Table 2), as well as the observed hydrograph
14
15 data provided by Grimaldi *et al.* (2012).
16

17
18 In the aforementioned relationship, the coefficient t_0 denotes a characteristic
19
20 travel time of the basin that corresponds to a unit runoff depth, $i_e = 1.0$ mm/h. Herein,
21
22 this will be referred to as *unit time of concentration*. As shown in Table 4, within the
23
24 examined sample, t_0 ranges from 1.4 to 7.6 h (4.0 h, on average). Its value is
25
26 systematically lower than the time of concentration estimated through the Giandotti
27
28 formula, and generally higher than the value provided by the Kirpich formula.
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30
31 On the other hand, the exponent β of Eq. (6) is a recession parameter, for which
32
33 there are quite different findings in the literature. It is well-known that according to the
34
35 kinematic wave theory, combined with the Manning's formula, this exponent should
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37 theoretically range from 0.25, for triangular channels, to 0.40, for overland flow and
38
39 wide rectangular channels. However, Saghafian *et al.* (2002), who applied a cell-by-cell
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41 approach to rectangular channels, estimated an exponent of 0.35, which is lower than
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43 the theoretical value of 0.40; this difference was attributed to the existence of non-wide
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45 channel network in their study basin. Meyersohn (2016) commented that natural
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47 channels will not exactly follow the power relationship. Other researchers, who
48
49 attempted to establish recession relationships for the lag time of the basin, have found
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51 exponent values much closer to ours. In particular, in a sample of five pasture basins in
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53 Australia, Askew (1970) has estimated exponents ranging from 0.190 to 0.305, before
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3 proposing the use of a constant value of 0.230. It is also interesting mentioning that
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5 Askew (1970) failed to associate the exponents to the channel characteristics, and
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7 commented that the latter may indicate that simplifying the computation of the
8
9 theoretical exponents can lead to incongruences between hydrology and hydraulics.
10
11 Finally, Aron *et al.* (1990) and Loukas and Quick (1996) have also tried to relate the lag
12
13 time with the effective rainfall intensity, concluding with a negatively power-law
14
15 function with exponents equal to 0.25 and 0.20, respectively.
16

17
18 In our sample, the exponent β varies from 0.126 to 0.264 (0.206, on average),
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20 thus being within the large range of the associated values that are reported in the
21
22 literature. We remind that in our methodology rectangular channels are assumed, in an
23
24 attempt to provide a parsimonious and, simultaneously, realistic, model structure. The
25
26 exponents found here deviate significantly from the theoretical value of 0.40, which is,
27
28 however, valid for wide shallow flow in rectangular channels. Apparently, for runoff
29
30 depths up to 100 mm applied to generally narrow channels, the flow will definitely not
31
32 be shallow, thus justifying the derivation of β values much lower than 0.40.
33
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35 36 37 **4.5 Sensitivity analysis**

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39 Initially, we investigated alternative schematizations of the Titarisios River basin, with
40
41 respect to the model configuration reported so far (herein referred to as “base”
42
43 scenario), comprising 12 junctions across the longest flow path, in order to evaluate the
44
45 effects of the level of discretisation on the model outcomes. In particular, a rough
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47 discretisation was employed, by assigning a coarser flow accumulation threshold, which
48
49 resulted to only six junctions (i.e., half of the base scenario), as well as a quite detailed
50
51 discretisation, comprising 19 junctions (Fig. 6). Then, calculations were repeated to
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53 obtain the regression parameters t_0 and β . As shown in Table 6, the unit time of
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55 concentration is quite overestimated, by considering a too rough discretisation, while
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3 the sensitivity of the exponent β is generally low. As expected, according to the
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5 theoretical justification discussed in Section 3.4, the implementation of a too detailed
6
7 spatial analysis, in terms of number of junctions and associated sub-catchments, has
8
9 negligible impacts to the model outcomes and thus the parameter values.
10

11 Taking now as example the river basin of Scoltenna upstream of Pievepelago,
12
13 we investigated next the sensitivity of the model against variations of the two roughness
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15 components, k and n , which are quite challenging to determine on the basis of field
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17 observations, and even more through remote information (e.g. satellite maps). In this
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19 context, we changed the typical values $k = 1.55$, $n = 0.033$ and the segments' widths of
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21 the test basin by 10 and 30%, repeated the calculations of the time of concentration as
22
23 function of runoff depth, and re-calculated the parameters t_0 and β . The results are
24
25 summarized in Tables 7 and 8, respectively.
26
27

28
29 In general, the relative impact of changing t_0 and β with respect to their base
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31 values, i.e. $t_0 = 2.47$ h and $\beta = -0.176$, is smaller than the relative change of the three
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33 input parameters. The surface roughness coefficient, k , is more sensitive than
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35 Manning's roughness coefficient, n and the river width. Moreover, the change of n
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37 results in systematic decreasing, up to negligible, changes on the time of concentration
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39 estimations, as the runoff intensity increases. The same applies for the sensitivity of the
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41 channel width, resulting to even more negligible changes (Table 9).
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45 **5. Regionalisation of regression parameters**

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48 In essence, the proposed GIS approach is physically-consistent and does not suffer from
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50 discretisation issues when changing pixel size. On the other hand, despite its simplicity
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52 and much lower computational effort in comparison with raster-based approaches, it
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54 requires GIS facilities that are not always available (or may not be attractive) for
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3 everyday engineering purposes, and may also require some manual interventions within
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5 the determination of model inputs. For this reason, analytical formulas, such as the ones
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7 illustrated in Table 1, are strongly preferred by practitioners, who wish to employ fast
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9 and easy recipes, with minimal data requirements and negligible computational effort.
10

11
12 Since both parameters t_0 and β exhibit significant variability across the study
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14 catchments, we attempted to provide regional relationships, by expressing them as
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16 functions of abstract catchment properties. Initially, we investigated whether these
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18 parameters are correlated with the geomorphological characteristics given in Tables 3
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20 and 4, and also looked for combinations of the above characteristics that ensure
21
22 significantly high correlations. Next, different parameterizations were tested, each one
23
24 calibrated against the results obtained by the application of the GIS procedure to the
25
26 sample of 30 catchments. Finally, the optimised regional formulas were contrasted
27
28 against existing literature approaches.
29
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31 32 **5.1 Correlation analysis**

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34 In our preliminary investigations, we computed the correlations between t_0 and β
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36 against the basins' geomorphological characteristics (catchment area, A , length of
37
38 longest flow path, L , average slope, J , width, b and roughness coefficient, n , across the
39
40 main stream), in an attempt to provide simple regression estimators of the two
41
42 parameters. In this context, the Pearson correlation coefficients were used, employed for
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44 linear and power-type dependencies. The correlation values are summarized in Table
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51 This preliminary analysis indicated that the variability of both parameters is well
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53 explained by the length and slope of the main stream, and less with the drainage area
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55 and the average width of the main stream. These outcomes are reasonable. Indeed, as
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3 the maximum flow length, L , increases, the travel time, defined as the ratio of L to an
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5 average velocity across the longest flow path, also increases. This time is also
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7 increasing function of the catchment's area, A , because in general, the large the extent
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9 of the basin the larger the maximum flow length is expected to be. Regarding the
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11 average slope, J , this is a key factor of the hydraulic response of a river, affecting both
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13 the characteristic time parameter, t_0 , and the exponent β , representing the recession of
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15 the travel time against the runoff intensity. The latter is also affected by the average
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17 width, b , of the main water course, which is direct outcome of the Manning's formula
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19 used within hydraulic calculations.
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24 **5.2 Calibration framework**

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26 From Table 9, it is also observed that t_0 and β are highly correlated with the (constant)
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28 t_c values estimated by the Giandotti and Kirpich formulas, comprising combinations of
29
30 the above geomorphological characteristics. Hence, we looked for composite
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32 expressions of t_0 and β that include these and additional characteristics, aiming to
33
34 ensure as much as more accurate predictions of the two variables, while at the same
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36 time remaining as parsimonious as possible. Apart from fitting the base values of t_0 and
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38 β , given in Table 4, we aimed to reproduce the individual (i_e, t_c) pairs of Table 5,
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40 which are direct outcomes of the GIS-based computational procedure (it is reminded
41
42 that t_0 and β are processed data, estimated through regression).
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46 In this context, a global optimization problem was formulated, by maximizing
47
48 the Nash-Sutcliffe efficiency (NSE) between the actual and simulated t_0 and β values
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50 of the 30 study catchments, and minimizing the total square error between the actual
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52 and simulated t_c values (six per catchment, 180 in total).
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After testing a large number of combinations, the following expression for the unit time of concentration, t_0 (h) was obtained:

$$t_0 = 9.00 n A^{0.028} L^{0.216} b^{0.081} J^{-0.500} \quad (7)$$

where A is the catchment area (km^2), L is the length of the longest flow path (km), b is the average width across the main water course (m), J is the average slope across the main water course (m/m) and n is the average Manning's roughness coefficient. This relationship ensures very satisfactory prediction of the actual t_0 values, as shown in Fig. 7, left, as the optimized NSE value is 0.923.

The optimized expression for the exponent is:

$$\beta = 0.40 - 0.80 A^{0.186} L^{-0.500} b^{-0.356} \quad (8)$$

which ensures an efficiency of 0.750. In the above relationship, the right term expresses the deviation from the theoretical upper value $\beta = 0.40$, which stands for shallow flow conditions over a flat bed of infinite width. From Eq. (8) we conclude that this deviation is explained by the catchment area, A , which is a measure of the discharge that enters the main water course, and the channel geometry, expressed by the length, L , and the average width, b . The wider is the channel, the smaller will be the deviation from the theoretical limit. We remark that most of the empirical relationships developed so far consider this parameter as constant, with the exception of Askew (1970), who attempted expressing the exponent β as function of A and L . However, since the available data sample was too small (five catchments), he did not recommend the use of his formula.

Following the Rational method assumptions, i.e. $Q = i_c A$, an empirical relationship to associate the time of concentration as function of the peak discharge at the basin outlet can also be extracted, i.e.:

$$t_c = t_0 \left(\frac{Q}{A}\right)^{-\beta} \quad (9)$$

Therefore, the time of concentration can be alternatively expressed as a negative power function of the peak discharge, also controlled by the exponent, β .

5.3 Comparison with literature approaches

Since the time of concentration is a theoretical quantity, referring to ideal conditions (i.e., uniform effective rainfall), a direct estimation of t_c on the basis of observed hydrological data is not possible. Consequently, it is not possible to establish a formal (i.e. data-based) validation procedure for evaluating the predictive capacity of Eq. (6), parameterized through the regional formulas (7) and (8). In this context, our validations were only based on comparisons against literature approaches, which are also subject to uncertainties and inaccuracies. In particular, we compared our outcomes with the processed flood data by Grimaldi *et al.* (2012), the theoretical formula by Meyersohn (2016), and the semi-empirical formula by Papadakis and Kazan (1987).

Grimaldi *et al.* (2012) have investigated dozens of observed rainfall-runoff events from four small-to-medium scale basins in the US (Cow Bayou, North Creek, Escondido Creek and North Elm Creek) and demonstrated that the time of concentration varies significantly for different peak discharge values. Within data processing, the authors employed a recursive filter to isolate the direct runoff and the SCS-CN method to extract the effective from the gross rainfall. To our knowledge, their analysis is unique as it provides such a clear picture of the variability of t_c against observed runoff data. Their outcomes were compared against our empirical formula (6), which parameters were derived by the regional Equations (7) and (8). The geomorphological characteristic of the four catchments and the derived t_0 and β values are given in Table 11. We remark that in the lack of related information, for the average channel width, reasonable values were assigned, accounting for the basin extent. As shown in Fig. 8, in

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3 all catchments the empirical Q vs. t_c relationship falls within the range of the observed
4 data. Actually, it tends to match the most extreme observed events, namely the ones
5 exhibiting the lowest response time with respect to the observed peak discharge, where
6 surface flow obviously prevails. This is not surprising, since our methodology follows
7 the Rational method assumptions, exclusively accounting for surface runoff and also
8 ignoring routing processes over sub-catchments that result to attenuated peaks and
9 increased response times.
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Meyersohn (2016) has employed a variable flow velocity approach to compute the travel time and construct time-area curves for a range of excess rainfall intensities. This method was tested in a 282 km² gauged watershed in Northern California, resulting to a similar relationship with Eq. (6), with $t_0 = 13.0$ h and $\beta = 0.294$. By employing the proposed regional formulas (7) and (8), the values $t_0 = 9.7$ h and $\beta = 0.296$ were obtained (Table 11). We remark that the recession parameters are identical, yet in our approach the unit time of concentration is smaller by about 30%. This deviation is absolutely reasonable, since it is well-known that a pixel-based approach provides larger response times with respect to channel-based approaches (Pavlovic and Moglen 2008). Furthermore, Meyersohn (2016) has incorporated a flow routing algorithm, in order to account for basin storage effects. As already mentioned, such effects are not modelled in our method, thus resulting to faster responses.

Additional comparisons were also made with the semi-empirical formula developed by Papadakis and Kazan (1987), for estimating the channel travel time across small catchments (Table 1). In Fig. 9 we contrast the unit time of concentration estimated by the two approaches at the 30 study areas. As shown, the Papadakis-Kazan formula provides systematically higher t_0 values. However, in the small and medium catchments the deviations are rather small, while they become quite larger as the

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3 catchment extent increases. This is reasonable, as the Papadakis-Kazan formula was
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5 developed on the basis of observed data extracted from very small basins (experimental
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7 setups and natural stream basins), with time of concentration values ranging within a
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9 couple of minutes. On the other hand, our regional formulas have been estimated by
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11 analysing a much larger extent of catchments, ranging within three orders of magnitude,
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13 i.e. from few km² to more than 1000 km².
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16 17 **6. Conclusions**

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19 The time of concentration, t_c , one of the fundamentals of hydrology, and an essential
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21 input of most widespread engineering recipes, has been reasonably characterised as a
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23 paradox. The existence of multiple, ambiguous and even illogical definitions, as well as
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25 numerous formulas providing significantly different estimations, and, the most
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27 importantly, its treatment as a constant of the basin rather than a variable quantity, has
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29 made t_c prone to severe misuse. In our work, we attempt to decode the paradox by
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31 taking into account the inherently dynamic behaviour of t_c , with its obvious dependence
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33 on the surface runoff generated in the basin.
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37 Apparently, this is not a novel viewpoint. For many decades, there is an ongoing
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39 discussion about the dependence of t_c (and the lag time, as well) to rainfall (or runoff)
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41 rate, and several methodologies have been proposed, ranging from theoretical and
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43 empirical formulae, to channel- and, more often, raster-based computational
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45 procedures,. However, many of these approaches are site-specific, while others (e.g.
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47 raster-based) are quite complicated and require several assumptions, which make them
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49 less attractive for the everyday practice. Moreover, they suffer from scaling issues, since
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51 the results are strongly affected by the pixel resolution. Finally, their physical
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3 consistency is questionable, since the velocity of each cell is independent of the velocity
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5 of the adjacent ones.

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7 Our objective is to provide a generalised yet simple methodology, based on a
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9 consistent interpretation of t_c , as the travel time across the hydraulically more distant
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11 path (typically assumed identical to the longest flow path), for a given excess rainfall
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13 that is uniformly generated over the catchment. By discretising this path into a relatively
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15 small number of sub-segments, and taking advantage of the well-known Rational
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17 method assumptions, we have developed a kinematic approach to estimate the flow
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19 velocity, and thus the travel time, from the headwater sub-catchment to the basin outlet.
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21 The preparation of (most of) model inputs and the computations have been automatised
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23 in a GIS environment. However, we emphasize that the implementation of the method
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25 should not be regarded as a black-box procedure, since several decisions are subject to
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27 engineering evidence; among them, the determination and configuration of the flow
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29 path up the headwater catchment, and the assignment of representative hydraulic
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31 properties and parameters to the modelling components (i.e., sub-reaches). This task is
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33 not straightforward, particularly in cases of long reaches with heterogeneous
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35 characteristics. On the other hand, our analyses at specific basins indicated that the
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37 model sensitivity against its inputs is relatively small; however, more extended
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39 investigations have to be employed to extract safe conclusions.
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44 By testing this methodology in a large number of Mediterranean basins,
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46 spanning from few up to more than 1000 km², we confirmed that the time of
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48 concentration is a negative power function of the runoff intensity. Taking advantage of
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50 the extended outcomes of our sample, we provide further insight into the two
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52 parameters of Eq. (6), i.e. the unit time of concentration t_0 (scale parameter) and the
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54 exponent β , and their association with the abstract geomorphological characteristics of
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3 the catchment (area, longest flow path length, average slope, channel width and
4 Manning's roughness coefficient). Looking for an even simpler alternative for the
5 analytical approach, we have developed the regional relationships (7) and (8) for
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7 estimating t_0 and β , respectively, which have been validated against experimental data
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9 and existing theoretical and semi-empirical relationships.
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14 Before closing this discussion, it is essential to be reminded that the time of
15 concentration is only a theoretical quantity, which is valid under ideal conditions. In
16 particular, we hypothesise a uniformly distributed surface runoff, which enters the main
17 stream of the catchment at the inflow points (junctions), and uniform flow conditions
18 across rectangular sub-reaches, where regulation and overbank flow processes are
19 ignored. In fact, in case of mild slopes, the routing mechanisms affect significantly the
20 flow dynamics, resulting in larger response times and attenuated peak flows. Moreover,
21 at each confluence junction we assume that the inlet time from each individual sub-
22 catchment is by definition lower than the accumulated travel time across the upstream
23 flow path. Yet, with few exceptions, this is a reasonable assumption, particularly when
24 the extent of sub-catchments is relatively small and one moves downstream. In this
25 context, the peak discharge given by Eq. (1) should be carefully interpreted as a
26 preliminary indicator of the catchment's response under the aforementioned
27 assumptions, but not to be used for design purposes.
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44 Nevertheless, implementing the concept of the varying time of concentration
45 into the practice still remains an open issue that needs to be addressed. In fact, this
46 requires a major shift from the widespread yet flawed hypothesis of the constant t_c , thus
47 also drifting substantial elements of hydrological modelling. For instance, in the context
48 of the rational method, key assumption is that the duration of design rainfall, d , should
49 be at least as long as the t_c , thus ensuring that the whole basin is contributing to
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2 runoff to the catchment outlet. If t_c is known a priori (e.g. through an empirical formula
3 that merely accounts for the basin's characteristics), the critical rainfall intensity, i , for
4 the return period of interest, T , is estimated by the idf expression, i.e. a function of the
5 form $i = f(d, T)$, by setting $d = t_c$. However, by considering t_c as function of the effective
6 rainfall, i.e. the product $c i$, the rational formula cannot be explicitly solved, thus
7 requiring few iterations to estimate to converge to the constant value of rainfall duration
8 and, consequently, a constant peak discharge (cf. Efstratiadis *et al.*, 2014).
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18 The implementation of the varying time of concentration is easier in the context
19 of continuous modelling, where the extraction of the effective from the gross rainfall
20 does not (and should not) depend on the value of t_c . Actually, the reasonable
21 dependence of the catchment's response time to the runoff produced over its surface
22 cannot only affect the spatiotemporal propagation of runoff. In the everyday
23 engineering practice, this is typically represented in a lumped manner, through the unit
24 hydrograph theory. The *dynamic unit hydrograph*, the shape of which follows the
25 variability of the excess rainfall intensity, is an evident consequence of the rainfall-
26 dependent time of concentration, and an essential component of this new working
27 paradigm. Ongoing research indicates that the adaptation of the varying t_c within well-
28 known modelling approaches is not a cumbersome task, and can ensure physically
29 consistency and thus reliable estimations in the context of hydrological design and flood
30 risk evaluations. The outcomes of this research will be reported in due course.
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47 **Acknowledgments**

48
49 The authors are grateful to Salvatore Grimaldi, Andrea Petroselli and Flavia Tauro for
50 providing the data used within section 5.3, as well as their kind comments, and the two
51 anonymous reviewers for their fruitful comments and suggestions that helped us
52 improve this article.
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Tables

Table 2. Literature approaches considering varying time of concentration, as function of a characteristic hydrological quantity.

Method	Formula	Remarks
Izzard (1946)	$t_c = 3.46 \frac{(0.0007i + c_r)L^{1/3}}{J^{1/3}} i^{-2/3}$ <p>L (km) and J (m/m) are the length and mean slope of the flow route, i (mm h⁻¹) is the rainfall intensity and c_r is a retardance coefficient depending on the surface (e.g. smooth asphalt, concrete, soil, dense green).</p>	Obtained experimentally from the American Bureau of Public Roads and refers to road or green areas without a developed hydrographic network. Suitable for a product $iL < 500$, where i in inches/h and L in ft.
US Army Corps of Engineers' (1954)	$t_c = \frac{1}{60} \left(10.57 + \frac{0.12}{S}\right) \left(\frac{L}{30.48}\right)^{0.55 - \left(\frac{0.001}{S}\right)} i^{-0.43}$ <p>L (m) and S (m/m) are the length and mean slope of the overland flow, i (mm h⁻¹) is the rainfall intensity.</p>	Obtained experimentally from airfield drainage data. Experiments were conducted in three concrete troughs (500 ft. in length) and flows were developed from rainfall simulators over the entire surface. Troughs sloped at 0.5, 1 and 2 %. Artificial roughness was generated by placing expanded metal plates, excelsior pads, and chicken wire in the troughs. A failed attempt was made to grow grass in one of the troughs.
Morgali & Linsley (1965)	$t_c = 0.12 \frac{n^{0.6} L^{0.6}}{J^{0.3}} i^{-0.40}$ <p>L (m) and J (m/m) are the length and mean slope of the hydraulically longest flow path, i (mm h⁻¹) is the rainfall intensity.</p>	Overland flow relation, obtained hydraulically from the kinematic wave and Manning's equation. Assumption of wide rectangular channels, so that hydraulic radius would be equal to the water depth.
Askew (1970)	$t_{lag} = 0.877 L^{0.80} J^{-0.33} q_{wm}^{-0.23}$ <p>L (km) and J (m/m) are the length and mean slope of the main stream and q_{wm} (m³ s⁻¹) is the weighted mean discharge.</p>	Obtained empirically from about 200 events in five small basins (0.4 to 90 km ²) near Sydney. Exponent varied in the basins but in

		the regression analysis was considered as constant.
Kadoya & Fukushima (1979)	$t_c = \frac{1}{60} C_T A^{0.22} i_E^{-0.35}$ <p>A (km²) is the catchment area, C_T is its storage coefficient (typically between 190 and 290 mm) and i_E (mm h⁻¹) is the effective rainfall intensity.</p>	Physically-based model, tested in natural catchments ranging in size from 0.5 to 143 km ² .
Papadakis & Kazan (1987)	$t_c = 2.154 \frac{n^{0.52} L^{0.5}}{J^{0.31}} i_E^{-0.38}$ <p>n is the Manning's coefficient, L (km) and J (m/m) are the length and mean slope of the flow path and i_E (mm h⁻¹) is the effective rainfall intensity.</p>	Developed from 84 small natural watersheds with an area of less than 500 acres and 291 experimental structures of fixed nature (e.g. slope, material) and very limited sizes (flow path length of maximum 500 ft.).
Aron <i>et al.</i> (1991)	$t_l = 0.0155 \frac{k^{0.42} n^{0.75} L^{0.58}}{c^{0.5} J^{0.38}} i_E^{-0.25}$ <p>$k = L/A^{0.6}$ is a watershed shape factor, n is the Manning's coefficient, L (m) and J (m/m) are the length and mean slope of the flow path, $c = R/a^{0.5}$ a channel shape factor and a the wetted cross-sectional channel area, and i_E (mm h⁻¹) is the effective rainfall intensity.</p>	Obtained analytically by assuming swale flow over the entire watershed.
Loukas & Quick (1996)	$t_l = 0.072 \left(\frac{B^{0.6}}{k^{0.4} K_{av}^{0.2} J^{0.2}} \right) i_E^{-0.20}$ <p>$B = L/A^{0.6}$ is a watershed shape factor, K_{av} is the average saturated hydraulic soil conductivity (mm h⁻¹), J (m/m) is the mean slope of the main stream, $k = R/a^{0.5}$ a channel shape factor and a the wetted cross-sectional channel area, and i_E (mm h⁻¹) is the effective rainfall intensity.</p>	Obtained analytically. Estimates lag time in forested mountainous catchments, where most of the flow is considered as subsurface. Hillslope runoff is an input to the main stream.

Table 2. Time of concentration formulae by Giandotti (1934) and Kirpich (1940).

Method	Formula
Giandotti (1934)	$t_c = (4A^{0.5} + 1.5L)/(0.8\Delta H^{0.5})$ <p>L (km) is the length and mean slope of the flow route and ΔH (m) is the elevation difference between the centroid of the basin and its outlet.</p>
Kirpich (1940)	$t_c = 0.0667L^{0.77}/S^{0.385}$ <p>L (km) and S (m/m) are the length and mean slope of the main stream.</p>

Table 3. Study basins and their geomorphological characteristics (A : area; L : length of longest flow path; J : average slope of main stream; Δz : difference between mean and outlet elevation; t_G , t_K : time of concentration estimated through the Giandotti and Kirpich formulas, respectively).

River basin (station)	Country	A (km ²)	L (km)	J (%)	Δz (m)	t_G (h)	t_K (h)
Rafina stream (outlet)	GR	123.3	29.6	3.0	226	7.4	3.5
Sarantapotamos (Gyra Stefanis)	GR	143.7	32.1	3.8	369	6.3	3.4
Xerias (Volos)	GR	111.5	34.0	4.4	466	5.4	3.3
Nedontas (Kalamata)	GR	114.8	21.6	7.5	819	3.3	1.9
Baganza (Marzolarà)	IT	125.5	32.7	3.7	538	5.1	3.5
Scoltenna (Pievepelago)	IT	129.7	14.9	11.7	583	3.5	1.2
Ceno (Ponte Lamberti)	IT	328.7	38.2	3.8	517	7.1	3.9
Nure (Ferriere)	IT	48.3	12.1	7.9	489	2.6	1.2
Tresinaro (Ca' De' Caroli)	IT	139.4	34.7	3.2	310	7.0	3.9
Rossenna (Rossenna)	IT	182.6	30.5	6.5	454	5.9	2.7
Leo (Fanano)	IT	36.9	10.6	18.7	752	1.8	0.8
Achelous (Mesochora dam)	GR	639.2	41.4	8.9	700	7.7	3.0
Lavino (Lavino di Sopra)	IT	82.8	25.8	4.5	241	6.0	2.7
Montone (Castrocaro)	IT	235.7	47.4	4.2	455	7.8	4.4
Tassobbio (Compiano)	IT	98.3	20.6	3.4	271	5.4	2.5
Enza (Vetto)	IT	293.5	31.5	5.5	551	6.2	2.9
Nure (Farini)	IT	200.6	24.4	5.0	513	5.1	2.5
Mella (Tavernole)	IT	130.1	20.1	8.6	751	3.5	1.7
Mella (Gardone)	IT	182.7	27.5	7.1	751	4.3	2.4
Aggitis (outlet)	GR	1853.6	59.4	3.2	381	16.7	5.9
Pamisos (Arios)	GR	564.1	46.7	4.4	332	11.3	4.3
Upper Peneus (Kalabaka)	GR	528.5	38.9	5.5	748	6.9	3.4
Upper Oglio (Ponte di Legno)	IT	122.2	17.5	11.6	1078	2.7	1.4
Xeros (Lazarides)	CY	67.5	12.9	12.4	436	3.1	1.1
Peristerona (Panagia Bridge)	CY	77.8	23.6	8.4	466	4.1	2.0
Titarisios (outlet)	GR	1813.0	93.5	3.0	569	16.3	8.4
Spercheios (outlet)	GR	1403.5	78.6	2.4	671	12.9	8.1
Peneus (Trikala)	GR	1372.9	77.7	2.3	638	13.1	8.1
Anavros (outlet)	GR	13.9	9.0	21.3	382	1.8	0.7
Enipeus (outlet)	GR	1140.5	120.3	2.5	302	22.7	11.1

Table 4. Model inputs (N : number of junctions; n : Manning's roughness coefficient; k : roughness coefficient of overland flow; b : average channel width), estimated regression parameters of travel time vs. runoff intensity, i.e. $t_c = t_0 i_e^{-\beta}$, and associated R^2 values.

River basin (station)	N	n	k (m s ⁻¹)	b (m)	t_0 (h)	β	R^2
Rafina stream (outlet)	10	0.029	1.55	12.9	5.14	0.243	0.987
Sarantapotamos (Gyra Stefanis)	12	0.034	1.56	11.4	4.74	0.232	0.985
Xerias (Volos)	13	0.031	1.55	12.1	4.76	0.208	0.980
Nedontas (Kalamata)	7	0.034	1.55	15.9	3.10	0.193	0.981
Baganza (Marzolarà)	9	0.032	1.64	27.8	4.34	0.260	0.990
Scoltenna (Pievepelago)	8	0.033	1.65	23.2	2.47	0.176	0.980
Ceno (Ponte Lamberti)	10	0.031	1.55	31.6	4.23	0.264	0.991
Nure (Ferriere)	8	0.036	1.65	14.1	1.95	0.190	0.976
Tresinaro (Ca' De' Caroli)	10	0.030	1.94	17.3	4.29	0.214	0.982
Rossenna (Rossenna)	10	0.033	1.42	23.5	4.04	0.230	0.988
Leo (Fanano)	5	0.032	1.63	10.9	1.50	0.128	0.967
Achelous (Mesochora dam)	14	0.030	1.83	22.0	2.85	0.229	0.982
Lavino (Lavino di Sopra)	10	0.031	1.52	8.7	4.01	0.159	0.968
Montone (Castrocaro)	9	0.031	1.55	20.4	5.67	0.241	0.989
Tassobbio (Compiano)	8	0.031	1.55	13.1	3.91	0.180	0.977
Enza (Vetto)	8	0.032	1.71	25.8	3.94	0.250	0.990
Nure (Farini)	12	0.033	1.70	28.9	4.12	0.196	0.980
Mella (Tavernole)	11	0.030	1.79	10.2	1.79	0.183	0.969
Mella (Gardone)	15	0.029	1.79	12.8	2.18	0.205	0.974
Aggitis (outlet)	14	0.031	1.55	18.1	6.49	0.230	0.982
Pamisos (Arios)	10	0.032	1.69	9.9	4.54	0.203	0.966
Upper Peneus (Kalabaka)	11	0.031	1.56	16.4	4.74	0.173	0.974
Upper Oglio (Ponte di Legno)	9	0.032	2.50	7.7	1.57	0.126	0.952
Xeros (Lazarides)	9	0.033	1.55	10.1	1.79	0.136	0.963
Peristerona (Panagia Bridge)	9	0.032	1.55	6.9	2.60	0.205	0.980
Titarisios (outlet)	12	0.031	1.55	16.0	5.93	0.220	0.974
Spercheios (outlet)	18	0.031	1.04	20.5	6.92	0.247	0.982
Peneus (Trikala)	15	0.029	1.56	22.8	7.26	0.223	0.981
Anavros (outlet)	4	0.035	1.56	9.5	1.42	0.187	0.987
Enipeus (outlet)	13	0.032	1.56	13.8	7.57	0.254	0.979

Table 5. Estimated time of concentration, t_c (h), for the applied runoff depths, P_e (mm).

River basin (station)	Runoff depth (mm)					
	1	5	10	25	50	100
Rafina stream (outlet)	9.55	4.87	3.82	2.92	2.49	2.19
Sarantapotamos (Gyra Stefanis)	8.34	4.37	3.48	2.71	2.34	2.09
Xerias (Volos)	7.85	4.39	3.61	2.92	2.58	2.35
Nedontas (Kalamata)	4.40	2.61	2.18	1.80	1.61	1.47
Baganza (Marzolarà)	7.95	3.88	2.99	2.22	1.85	1.59
Scoltenna (Pievepelago)	3.23	2.02	1.72	1.45	1.31	1.21
Ceno (Ponte Lamberti)	7.77	3.75	2.87	2.11	1.75	1.50
Nure (Ferriere)	2.48	1.46	1.23	1.02	0.92	0.85
Tresinaro (Ca' De' Caroli)	7.00	3.86	3.14	2.52	2.21	2.00
Rossenna (Rossenna)	6.68	3.57	2.86	2.24	1.92	1.70
Leo (Fanano)	1.70	1.20	1.08	0.97	0.91	0.86
Achelous (Mesochora dam)	4.29	2.25	1.80	1.41	1.23	1.10
Lavino (Lavino di Sopra)	5.65	3.62	3.15	2.72	2.51	2.37
Montone (Castrocaro)	10.71	5.55	4.38	3.36	2.86	2.50
Tassobbio (Compiano)	5.73	3.49	2.96	2.49	2.25	2.08
Enza (Vetto)	6.79	3.42	2.67	2.02	1.70	1.47
Nure (Farini)	6.34	3.70	3.09	2.54	2.27	2.07
Mella (Tavernole)	2.24	1.32	1.12	0.94	0.86	0.80
Mella (Gardone)	2.95	1.63	1.34	1.10	0.98	0.90
Aggitis (outlet)	12.53	6.53	5.22	4.09	3.56	3.20
Pamisos (Arios)	7.49	4.08	3.35	2.76	2.50	2.33
Upper Peneus (Kalabaka)	7.12	4.42	3.78	3.21	2.92	2.72
Upper Oglio (Ponte di Legno)	1.81	1.26	1.13	1.02	0.97	0.93
Xeros (Lazarides)	2.11	1.45	1.29	1.14	1.07	1.02
Peristerona (Panagia Bridge)	3.64	2.06	1.69	1.38	1.22	1.11
Titarisios (outlet)	10.96	5.75	4.63	3.71	3.29	3.03
Spercheios (outlet)	14.56	7.14	5.55	4.25	3.65	3.28
Peneus (Trikala)	14.15	7.54	6.07	4.82	4.22	3.81
Anavros (outlet)	1.64	1.02	0.86	0.71	0.63	0.57
Enipeus (outlet)	17.07	8.02	6.14	4.65	4.01	3.63

Table 6. Sensitivity analysis of the river discretisation by means of variation of parameters t_0 and β at Titarisios river basin, with respect to their "base" number of junctions, $N = 12$.

	$N = 6$	$N = 12$	$N = 19$
t_0 (h)	6.96	5.93	5.94
β	0.238	0.220	0.219

Table 7. Sensitivity analysis of surface roughness coefficients by means of variation of parameters t_0 and β at Scoltenna with respect to the “base” value, $k = 1.55$.

	-30%	-10%	Base value	+10%	+30%
t_0 (h)	2.95	2.60	2.47	2.37	2.20
β	0.158	0.170	0.176	0.180	0.188

Table 8. Sensitivity analysis of Manning’s roughness coefficient by means of variation of parameters t_0 and β at Scoltenna with respect to the “base” value, $n = 0.033$.

	-30%	-10%	Base value	+10%	+30%
t_0 (h)	2.18	2.38	2.47	2.56	2.72
β	0.158	0.170	0.176	0.180	0.188

Table 9. Sensitivity analysis of the channel widths by means of variation of parameters t_0 and β at Scoltenna with respect to the “base” value, $b = 23.2$ m.

	-30%	-10%	Base value	+10%	+30%
t_0 (h)	2.28	2.41	2.47	2.53	2.63
β	0.162	0.172	0.176	0.179	0.185

Table 10. Linear and power-type correlations between parameters t_0 and β and the key geomorphological characteristics of study basins (catchment area, length of longest flow path, and average slope, width, and Manning’s coefficient of the main stream), as well as the time of concentration estimations by Giandotti and Kirpich.

		A	L	J	b	n	t_G	t_K
t_0	Linear	0.725	0.854	-0.789	0.337	-0.357	0.859	0.898
	Power	0.754	0.883	-0.931	0.463	-0.368	0.905	0.933
β	Linear	-0.378	-0.553	0.638	0.586	0.226	-0.532	-0.586
	Power	-0.508	-0.665	0.676	-0.587	0.227	-0.645	-0.694

Table 11. Catchment characteristics, source data, and estimated parameters t_0 and β within validation. Channel widths are approximately estimated.

River basin	Source data	A (km ²)	L (km)	J (%)	b (m)	n	t_0 (h)	β
Cow Bayou	Grimaldi <i>et al.</i> (2012)	13.1	7.4	5.9	15.0	0.04	3.05	0.221
North Creek	Grimaldi <i>et al.</i> (2012)	59.0	18.5	5.2	20.0	0.04	4.24	0.265
Escondido	Grimaldi <i>et al.</i> (2012)	22.8	8.6	2.9	15.0	0.04	4.58	0.216
North Elm Creek	Grimaldi <i>et al.</i> (2012)	119.5	35.4	1.4	25.0	0.04	9.76	0.297
Coyote Creek	Meyersohn (2016)	282.0	47.9	1.7	25.0	0.04	9.69	0.296

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Figures

Fig. 1: Graphical representation of the time of concentration rationale.

Fig. 2: ArcGIS model for river delineation and spatial calculations in Model Builder.

Fig. 3: Reach-by-reach application of the computational procedure at the Nedontas river basin, for $P_e = 10$ mm.

Fig. 4: Location of Mediterranean study catchments.

Fig. 5: Estimated and simulated time of concentration as a function of runoff intensity for the basins of Nedontas (left) and Enipeus (right).

Fig. 6: Different discretisation approaches for Titarisios river basin, considering 6, 12 and 19 junctions across the longest flow path.

Fig. 7: Comparison of actual (i.e. estimated through the GIS procedure) and simulated (by the corresponding regional formulas) parameters t_0 (left) and β (right).

Fig. 8: Comparison of scatter plots published by Grimaldi *et al.* (2012) and the theoretical model (continuous line) derived through the empirical formula (6).

Fig. 9: Comparison of unit time of concentration values across study basins calculated with the empirical formula of Papadakis-Kazan (1987) and by the regional eq. (6).

Figures

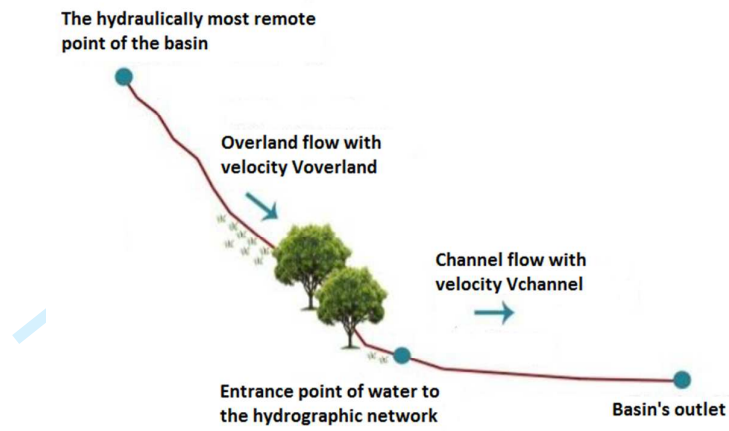


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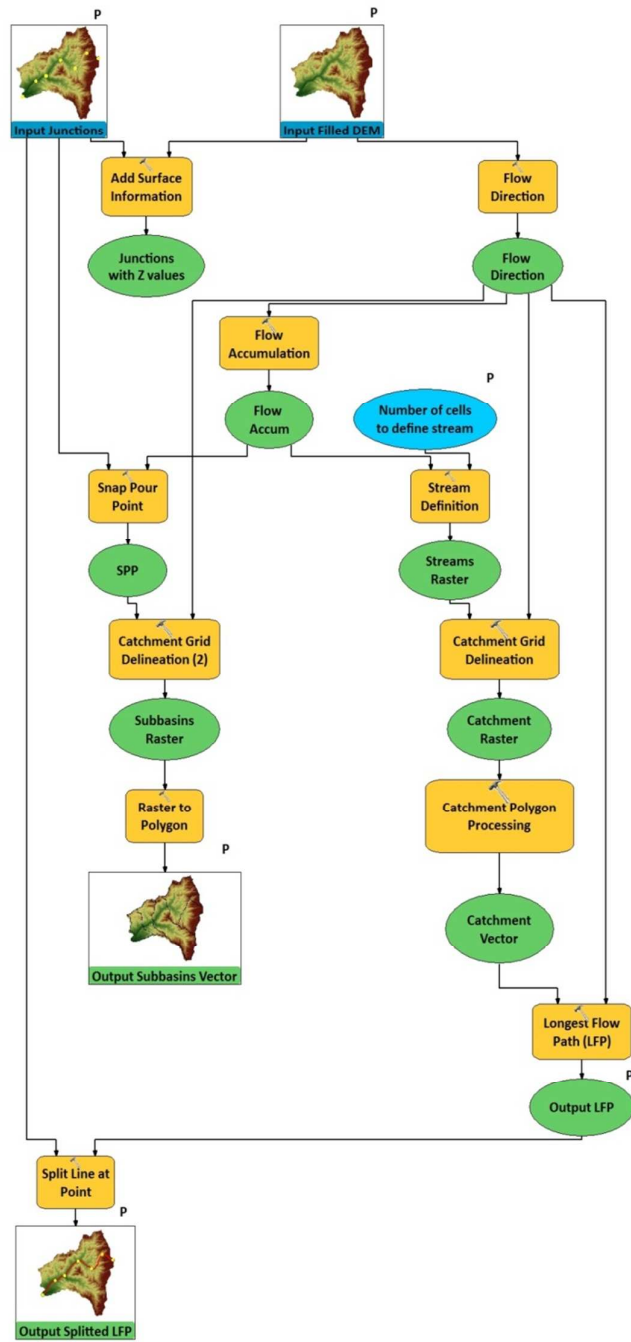


Fig. 2: ArcGIS model for river delineation and spatial calculations in Model Builder.

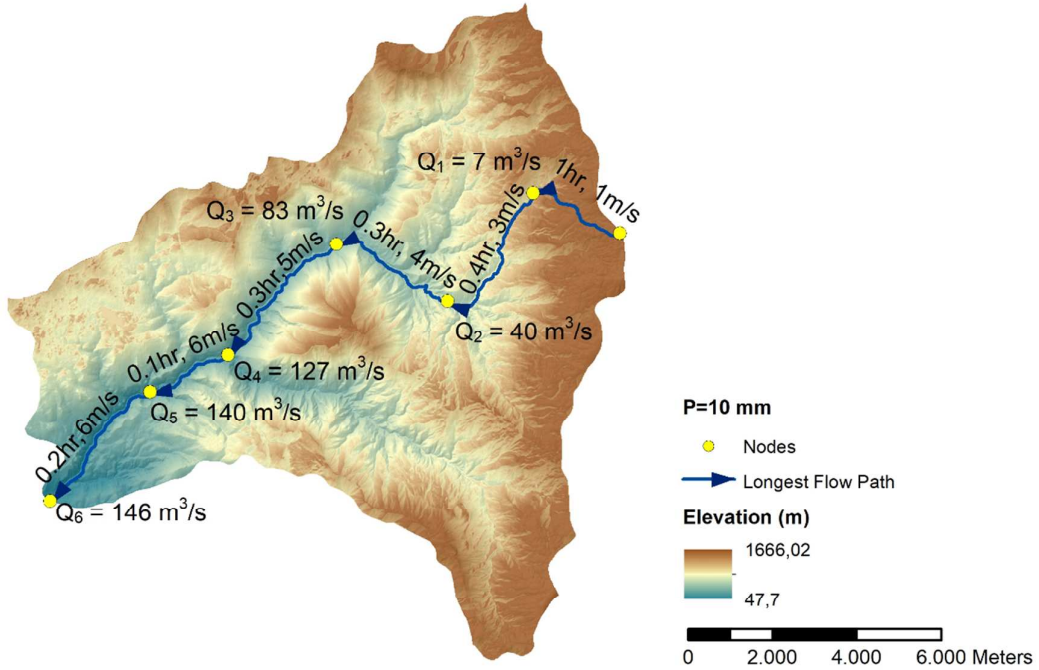


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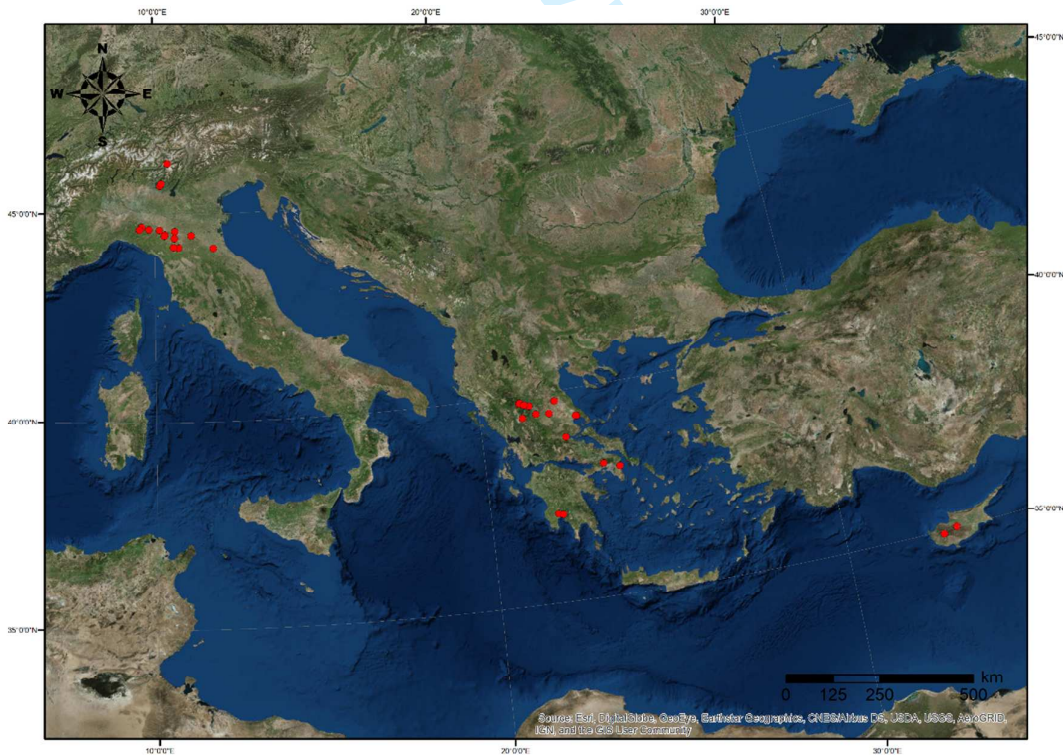


Fig. 4: Location of Mediterranean study catchments.

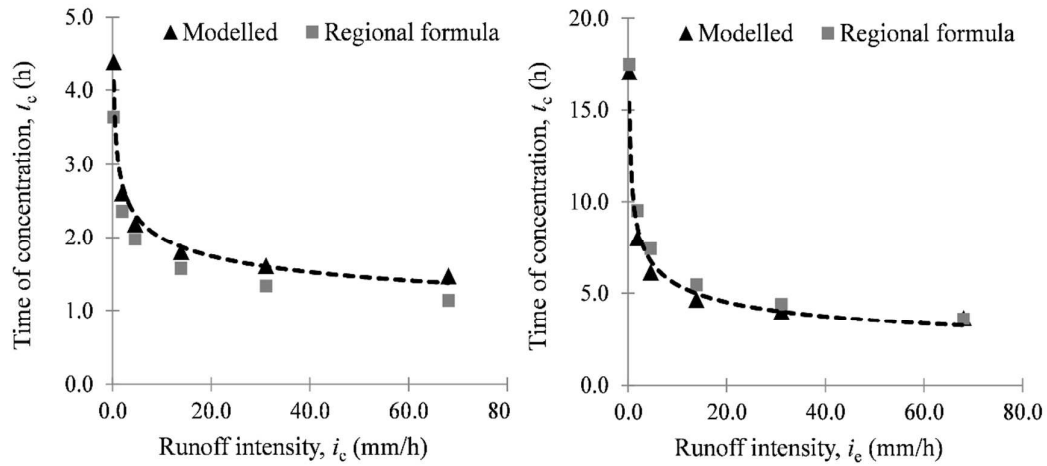


Fig. 5: Estimated and simulated time of concentration as a function of runoff intensity for the basins of Nedontas (left) and Enipeus (right).

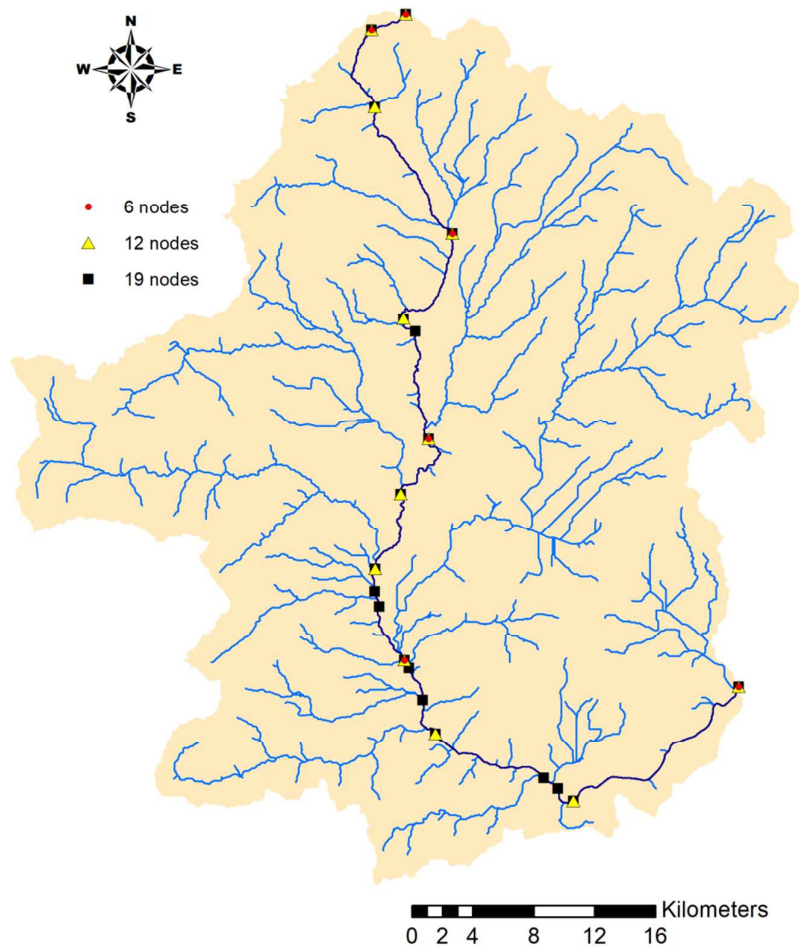


Fig. 6: Different discretisation approaches for Titarisios river basin, considering 6, 12 and 19 junctions across the longest flow path.

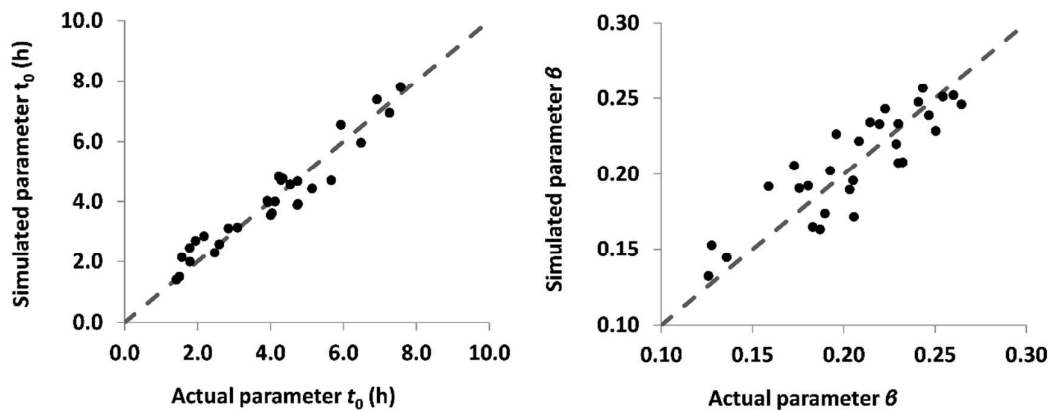


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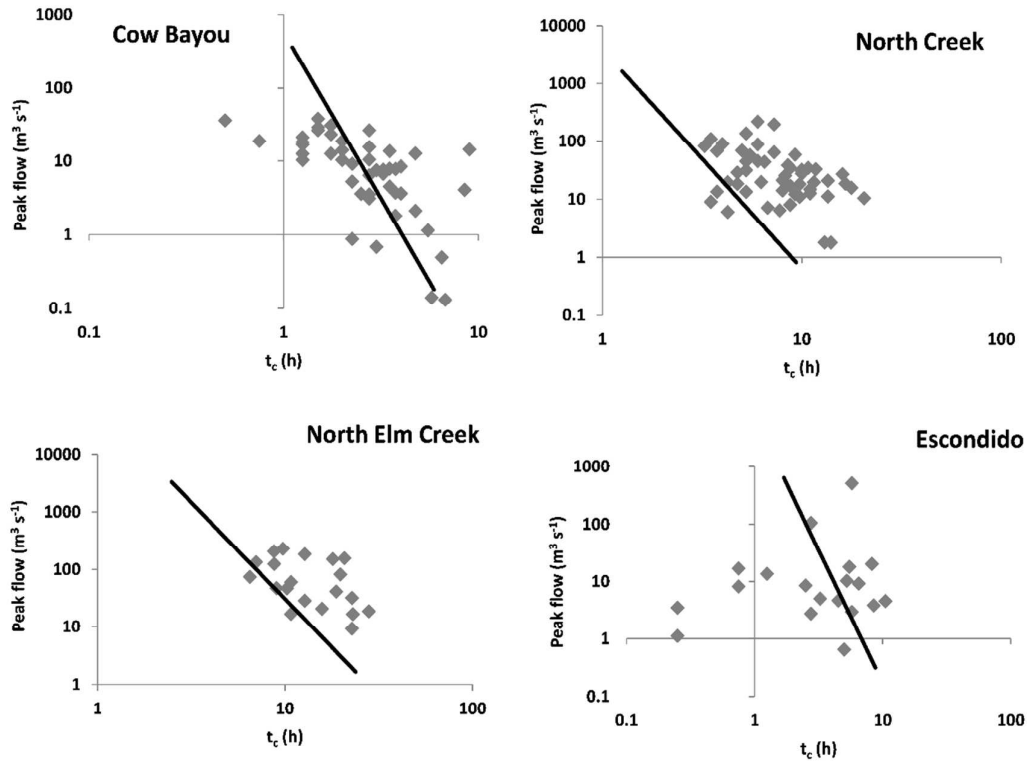


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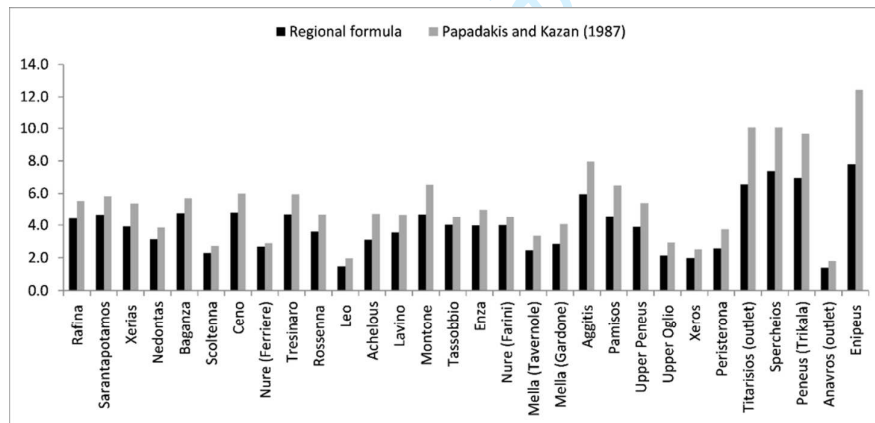


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