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A process at the annual scale	Xi
The mean of X_i	$\mu := E[X_i]$
The standard deviation of X_i	$\sigma := \sqrt{\operatorname{Var}[X_i]}$
The aggregated process at a multi-year cale $k \ge 1$	$Z_{1}^{(k)} := X_{1} + \dots + X_{k}$ $Z_{2}^{(k)} := X_{k+1} + \dots + X_{2k}$ \vdots $Z_{i}^{(k)} := X_{(i-1)k+1} + \dots + X_{ik}$
The mean of $Z_i^{(k)}$	$E[Z_{i}^{(k)}] = k \mu$
ne standard deviation of $Z_i^{(k)}$	$o^{(k)} := \sqrt{\operatorname{Var}\left[Z_i^{(k)}\right]}$
if consecutive X_i are independent	$o^{(k)} = \sqrt{k}\sigma$
if consecutive X_i are positively correlated	$\sigma^{(k)} > \sqrt{k}\sigma$
if X_i follows the Hurst phenomenon	$\sigma^{(k)} = k^{\mathcal{H}} \sigma (0.5 < \mathcal{H} < 1)$
xtension of the standard deviation scaling nd definition of a simple scaling stochastic rocess (SSS)	$(Z_{i}^{(k)} - k\mu) \stackrel{d}{=} \left(\frac{k}{l}\right)^{H} (Z_{j}^{(l)} - l\mu)$ for any scales k and l

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The power-laws of the second-order properties of an SSS process

The standard deviation of $Z_i^{(k)}$ (a power law of scale k)	$\sigma^{(k)} = k^{H} \sigma$
The lag- <i>j</i> autocorrelation of $Z_i^{(k)}$ (a power law of lag <i>j</i> ; independent of scale <i>k</i>)	$ \rho_{j}^{(k)} = \rho_{j} \approx H(2H-1) j ^{2H-2} $
The lag- <i>j</i> autocovariance of $Z_i^{(k)}$ (a power law of scale <i>k</i> and lag <i>j</i>)	$\gamma_{j}^{(k)} \approx H(2H-1) \gamma_{0} k^{2H} j ^{2H-2}$
The power spectrum of $Z_i^{(k)}$ (a power law of scale k and frequency ω)	$s_{\gamma}^{(k)}(\omega) \approx 4(1-H) \gamma_0 k^{2H} (2\omega)^{1-2H}$

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Algorithm 2: The weighted sum of three Markovian processes 0.8 õ An SSS process X_i can be approximated by Exact Autocorrelation, 0.7 the sum of three AR(1) processes: Approximation 0.6 $X_i = A_i + B_i + C_i$ 0.5 with lag one autocorrelations respectively 0.4 $\rho = 1.52 \ (H - 0.5)^{1.32}$, = 0.90.3 0.2 $\varphi = 0.953 - 7.69 (1 - H)^{3.85}$ H = 0.7H = 0.80.1 0.932 + 0.087 H, $H \le 0.76$, 0 ξ= 10 100 1000 Lag, j 0.993 + 0.007 *H*, *H* > 0.76 and variances respectively, Degree of $(1 - C_1 - C_2) \gamma_0, \quad C_1 \gamma_0,$ $C_2 \gamma_0$ approximation of the where c_1 and c_2 are estimated so that the SSS autocorrelation autocorrelation of the sum of the three attained by the use of processes three AR(1) processes $\rho_{i} = (1 - c_{1} - c_{2})\rho^{j} + c_{1} \varphi^{j} + c_{2} \xi^{j}$ match the theoretical SSS autocorrelation for lags 1 and 100 Source: Koutsoyiannis (2002) D. Koutsoyiannis, Simple methods to generate time series with scaling behaviour 16





Algorithm 3: Parameter estimation and generation procedure

In each disaggregation step the first lower-level variable, $Z_{2i-1}^{(k/2)}$, is generated from

$$Z_{2\,i-1}^{(k/2)} = a_2 Z_{2\,i-3}^{(k/2)} + a_1 Z_{2\,i-2}^{(k/2)} + b_0 Z_i^{(k)} + b_1 Z_{i+1}^{(k)} + V$$

and the second one, $Z_{2i}^{(k/2)}$, from

$$Z_{2 i-1}^{(k/2)} + Z_{2 i}^{(k/2)} = Z_{i}^{(k)}$$

where parameters a_2 , a_1 , b_0 koi b_1 and the variance of the random variable *V* are estimated in terms of correlations $\text{Corr}[Z_{2\,i-1}^{(k/2)}, Z_{2\,i-1+j}^{(k/2)}] = \rho_j$ and the variance $v_0^{(k/2)}$ according to

$$\begin{bmatrix} a_{2} \\ a_{1} \\ b_{0} \\ b_{1} \end{bmatrix} = \begin{bmatrix} 1 & \rho_{1} & \rho_{2} + \rho_{3} & \rho_{4} + \rho_{5} \\ \rho_{1} & 1 & \rho_{1} + \rho_{2} & \rho_{3} + \rho_{4} \\ \rho_{2} + \rho_{3} & \rho_{1} + \rho_{2} & 2(1 + \rho_{1}) & \rho_{1} + 2\rho_{2} + \rho_{3} \\ \rho_{4} + \rho_{5} & \rho_{3} + \rho_{4} & \rho_{1} + 2\rho_{2} + \rho_{3} & 2(1 + \rho_{1}) \end{bmatrix}^{-1} \begin{bmatrix} \rho_{2} \\ \rho_{1} \\ 1 + \rho_{1} \\ \rho_{2} + \rho_{3} \end{bmatrix}$$
$$\operatorname{Var}[V] = \gamma_{0}^{(k/2)} (1 - [\rho_{2}, \rho_{1}, 1 + \rho_{1}, \rho_{2} + \rho_{3}] [a_{2}, a_{1}, b_{0}, b_{1}]^{T})$$

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Algorithm 4: Filtering white noise through a symmetric moving average filter

The symmetric moving average (SMA) generating C_{ij}^{α} scheme (Koutsoyiannis, 2000) transforms a white noise sequence V_i into a process X_i with given autocorrelation function by

$$X_i = \sum_{j=-q}^{q} a_{|j|} V_{i+j}$$

where a_j are weighting factors whose number q is theoretically infinite but in practice can take a finite value. For an SSS process:

$$a_{j} \approx \frac{\sqrt{(2-2H)} \gamma_{0}}{3-2H} \times (|j+1|^{H+0.5} + |j-1|^{H+0.5} - 2|j|^{H+0.5})$$

The method can also preserve the skewness ξ_X of X_i assuming that the white noise has skewness ξ_ν determined from

$$\left(a_0^3 + 2\sum_{j=1}^q a_j^3\right)\xi_V = \xi_X \gamma_0^{3/2}$$









Conclusion

- The scaling behaviour seems to be an omnipresent characteristic of hydroclimatic time series
- This behaviour manifests the great uncertainty and unpredictability of the hydroclimatic processes
- In simulations of hydrosystems it is important to preserve the scaling behaviour (the Hurst phenomenon should not be regarded as "a ghost to be conjured away"; Klemeš, 1974)
- This is not a difficult task and can be achieved with simple algorithms even in a spreadsheet environment
- Even a simple two-dimensional deterministic toy model can generate series respecting the scaling behaviour of hydroclimatic processes
- In a stochastic context, the scaling behaviour can be represented by the weighted sum of three Markovian processes
- Stepwise disaggregation can yield another simple method to generate time series with scaling behaviour
- Symmetric moving average filtering of white noise yields another simple method to generate simple scaling time series

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This presentation is available on line at http://www.itia.ntua.gr/e/docinfo/607/

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