

**Motivation**

In a separate oral communication (Veneziano et al., "Annual Rainfall Maxima: Large-deviation Alternative to Extreme-Value and Extreme-Excess Methods"), we show that, at least for scale-invariant rainfall models, classical extreme value (EV) and excess (EE) theories do not apply to the annual rainfall maxima (AM) under multifractal rainfall; a more comprehensive theoretical setting to study annual maxima is provided by large-deviation (LD) theory. Here we present some practical implications of these theoretical findings for the estimation of the Intensity-Duration-Frequency (IDF) Curves.

- According to conventional EV and EE thinking, at least for short averaging durations  $d$ ,
- (1) the annual maximum rainfall intensity in  $d$ ,  $I_{year}(d)$ , has generalized extreme value (GEV) distribution,
  - (2) the excess of the average intensity in  $d$ ,  $I(d)$ , above a level  $u$  on the order of the annual maximum has generalized Pareto (GP) distribution,
  - (3) the GEV and GP distributions have the same shape parameter  $k$ ,
  - (4)  $k$  is determined by the upper tail of  $I(d)$ .

- Application of LD theory and multifractal analysis show that the above is incorrect and,
- (1) for  $d \rightarrow 0$ ,  $I_{year}(d)$  has  $EV2(k)$  distribution where,
    - $k$  depends on the distribution of the scaling factor not the upper tail of  $I(d)$ ,
    - $k$  is always higher than the value from EV and EE theories,
  - (2) for finite  $d$ , the distribution of  $I_{year}(d)$  between return periods of practical interest is well approximated by an  $EV2(k)$  distribution where,
    - $k(d)$  depends on  $d$  and the MF parameters,
    - $k(d)$  is nearly universal.

**Estimation of IDF values**

Let  $i(d, T)$  be the average rainfall intensity in an interval of duration  $d$  with return period  $T$ . The IDF curves are plots of  $I(d, T)$  against  $d$  for different fixed  $T$ . We compare several estimators of  $I(d, T)$ . Some are classical and other are new.

**Classical Estimators** use either Annual Maxima (AM) or Marginal Excesses (ME). The distribution of the annual maxima is assumed to be GEV type

$$GEV \rightarrow F_{year}(i) = \exp\left\{-\left[1+k\left(\frac{i-\mu}{\sigma}\right)\right]^{-1/k}\right\}, \text{ params: } \mu, \sigma, k \quad (1)$$

and the distribution of the marginal excesses above threshold  $u$  is assumed to be GP

$$GP \rightarrow F_i(i) = 1 - \left[1+k\frac{i-u}{\sigma}\right]^{-1/k}, \text{ params: } \sigma, k \quad (2)$$

When using Eq.1  $I(d, T)$  is obtained as the upper  $1/T$ -quantile of  $I_{year}(d)$ , whereas in the case of Eq. 2  $I(d, T)$  is the  $(1/\lambda T)$ -upper quantile of  $I$ ,  $\lambda$  being the rate of which the threshold  $u$  is exceeded.

The parameters in Eqs. 1 and 2 are fitted by Maximum Likelihood (ML) or by Probability Weighted Moments (PWM). In Eq. 2, we have fixed  $u$  such that the estimator of  $k$  has the minimum RMSE.

**Alternative Estimators** include (i) methods that obtain  $k$  from multifractal theory ( $m_f$ ) and (ii) estimators that use different distributional assumptions.

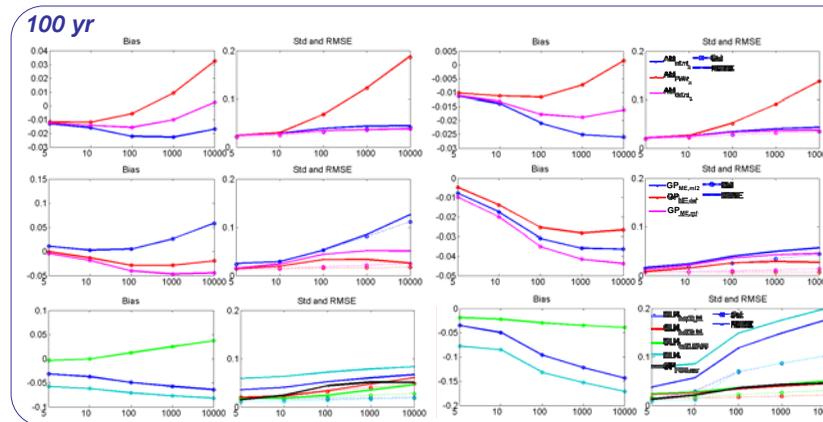
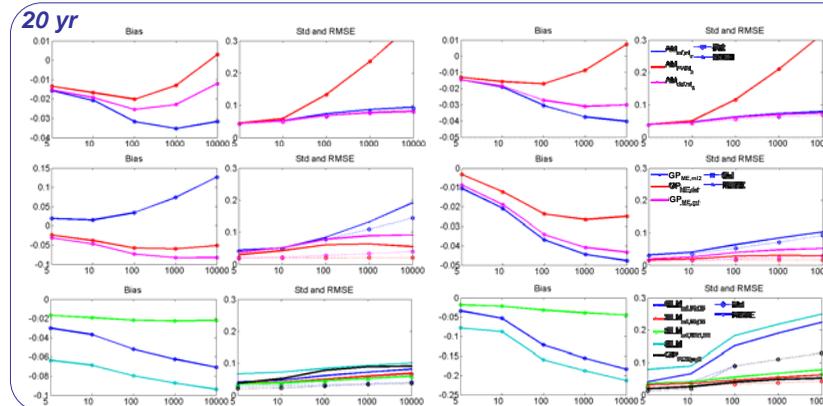
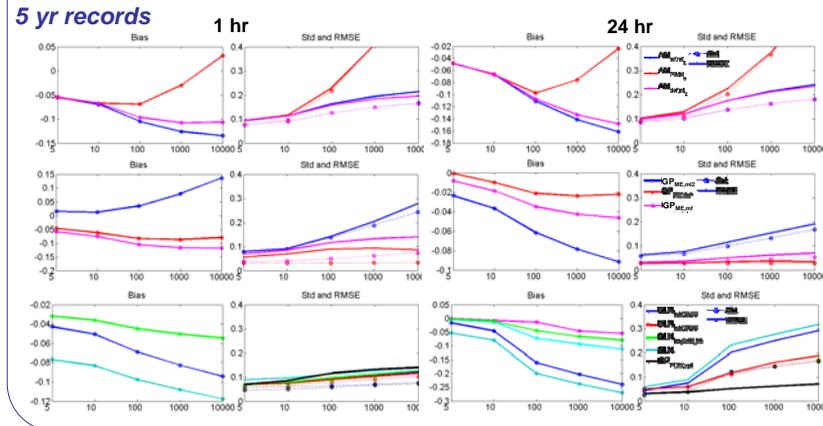
**Methods (i)** retain the use of GEV for the annual maxima and GP for the marginal excesses. The important difference is that  $k$  is derived from the scaling parameters of a beta-lognormal MF model (see above oral presentation). We refer to this estimator as  $k_{mf}(d)$ . Another possibility is to use a "universal" default value  $k_{def}(d)$ , obtained as the average of  $k_{mf}(d)$  over many sites (see above oral presentation). The other parameters are estimated by ML.

**Methods (ii)** are based on the assumption that the marginal excess has a truncated lognormal distribution and therefore that the upper tail of the marginal distribution of  $I(d)$  above some threshold  $u$  has scaled lognormal (SLN) form

$$SLN \rightarrow F_i(i) = 1 - P_1 \cdot \left\{1 - \Phi\left(\frac{\ln(i) - \mu}{\sigma}\right)\right\}, \text{ params: } P_1, \mu, \sigma \quad (3)$$

where  $\Phi$  is the standard normal distribution. This SLN distribution is supported by empirical evidence and asymptotic ( $d \rightarrow 0$ ) multifractal analysis. To obtain the distribution of the annual maximum  $I_{year}(d)$ , the distribution in Eq. 3 is raised to a power  $n(d)$  that is either estimated by ML using AM data or fixed to  $1/d$  with  $d$  expressed in years. The parameters ( $\mu$ ,  $\sigma^2$ ) are estimated by ML using marginal excess data and  $P_1$  is either estimated from MF theory as  $P_{mf}$  (like  $k$  in Eq. 2) or found by ML together with  $\mu$  and  $\sigma^2$ .

- Legend**
- AM<sub>mf,m2</sub> – GEV fitted to AM data with  $k_{mf}$  and the other 2 parameters estimated by ML.
  - AM<sub>def,m2</sub> – GEV fitted to AM data with  $k_{def}$  and the other 2 parameters estimated by ML.
  - AM<sub>PWM3</sub> – GEV fitted to AM data, 3 parameters (including  $k$ ) are estimated by PWM.
  - GP – GP fitted to ME data with both parameters estimated by ML.
  - GP<sub>ME,m2</sub> – GP fitted to ME data with  $k_{def}$  and the remaining parameter  $s$  estimated by ML.
  - GP<sub>ME,def</sub> – GP fitted to ME data with  $k_{mf}$  and the remaining parameter  $s$  estimated by ML.
  - GP<sub>ME,mf</sub> – SLN fitted to ME data, all 3 parameters including  $n(d)$  fitted to the ME data with threshold equal to the XX quantile for  $d=1hr$  and the YY quantile for  $d=24hr$ .
  - SNL<sub>n(d),XX,YY</sub> – SLN distribution with  $n(d) = 1/d$ , XX=0.8 and YY=0.6.



**Method for assessing different estimators**

- All the estimator of  $I(d, T)$  are applied to records simulated as uninterrupted sequences of iid multifractal cascades of the beta-lognormal type with parameters  $C_\beta=0.5$ ,  $C_{LN}=0.04$ . The duration of each cascade is 15 days.
- The figures show the BIAS, STD and RMSE of  $\log_{10}[I(d, T)]$  for  $d=1$  hr and 24 hr and return periods  $T$  ranging from 5 to 10000 years ( $T$  varies along the horizontal axes).
- Results are shown for record lengths of 5, 20 and 100 years (50 simulations each).
- For each simulated record the  $I(d, T)$  estimates are compared with the corresponding exact values obtained analytically by the method of Langousis et al. 2007.

**Results and Conclusions**

Results are displayed in 3 boxes, each for one record length. Within each box, the first row considers estimators that use the AM values and the GEV distribution in Eq. 1, the second row uses the ME values and the GP distribution in Eq.2, and the third row is for estimators that use the SLN distribution of the excesses in Eq. 3.

(See legend of the figures for more details). The results show that the estimators that either fix  $k$  to default values or estimate  $k$  using the multifractal method clearly outperform the traditional estimators. This is especially true for long return periods. As expected the relative accuracy of methods based on annual maxima increases as the record length increases. More detailed comments follow.

**For short records (5-20 years):**

- The estimator based on ME with  $k=k_{def}$ ,  $GP_{ME,def}$ , performs best, mostly because in this case  $k_{def}$  is close to the optimal  $k$ . The new estimator that uses  $k=k_{mf}$ ,  $GP_{ME,mf}$ , is the next high performer, with a generally small bias and even smaller std. The traditional estimator  $GP_{ME,m2}$  (with  $k$  and  $\sigma$  estimated by ML using the optimum threshold  $u$  as described above) has a relatively small bias but a high variance and performs much worse than  $GP_{ME,mf}$ .
- $AM_{mf,m2}$  performs nearly as well as  $GP_{ME,mf}$  for records of duration  $\geq 5$  years ( $d=1$  hr) or  $\geq 20$  years ( $d=24$  hr). This is true especially for long return periods. This result was partly expected as  $GP_{ME,mf}$  and  $AM_{mf,m2}$  share the same multifractal estimator of  $k$ .
- the traditional estimators based on AM data,  $AM_{PWM3}$  and  $AM_{m3}$  are highly erratic.
- the estimator based on the SLN model in Eq. 3 performs best when  $n(d)$  is estimated from annual maximum data ( $SLN_{n(d)}$  in figures) as opposed to being fixed to  $1/year/d$  (SLN). For  $d=1hr$  these estimators perform better than the GP estimators, whereas for  $d=24$  hr the performance is comparable.

**For long records (>50 years)**

- The AM estimator with  $k_{mf}$ ,  $AM_{mf,m2}$ , performs similarly to  $GP_{ME,mf}$ , it may even outperform  $GP_{ME,mf}$  for long return periods.

**References**

1. Veneziano, D., A. Langousis and C. Lepore (2009) Annual Rainfall Maxima: Large-Deviation Alternative to Extreme-Value and Extreme-Excess Methods, European Geosciences Union, Vienna, Austria, April 2009.
2. Langousis A, D. Veneziano, P. Furcolo, and C. Lepore (2007) Multifractal Rainfall Extremes: Theoretical Analysis and Practical Estimation, *Chaos Solitons and Fractals*, doi:10.1016/j.chaos.2007.06.004.

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