

A disaggregation model for storm hyetographs

(Developed in the framework of the AFORISM project)

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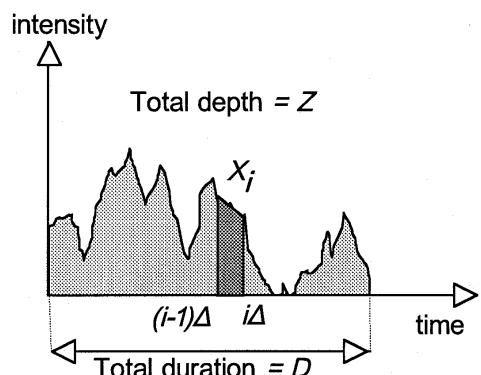
Model requirements

General characteristics:

- Random shape of hyetograph
- Reproduction of the hyetograph at an incremental basis (Δ)
- Compatibility with various rainfall models
- Simplicity
- Parsimony of parameters

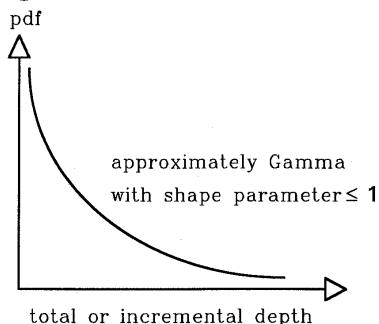
Special characteristics

- Event based
 - Given duration, D
 - Given total depth, Z
- ↓
Disaggregation model



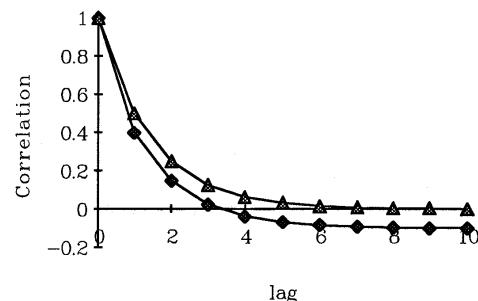
General structure of total and incremental depths

Marginal distribution



Correlation structure

(incremental depths)



Disaggregation models are not exact

General form

$$\underbrace{X_1 + X_2 + \dots + X_k}_{\text{lower level variables of } k \text{ sub-periods}} = \underbrace{Z}_{\text{higher level variable of one period}}$$

General problems

- Skewed distributions
- Additive property (if applied to nonlinearly transformed variables)
- Correlations between variables located at different periods

Exceptions, where d.m. are exact

1. X_i are normal, independent of variables of other periods
2. X_i are independent gamma variables with common scale parameter

Theoretical background

Let

- X_i^* : Independent, Gamma(κ_i, λ) ($i = 1, \dots, k$)
- Z : Independent of X_i^* , Gamma(κ, λ), where $\kappa = \sum_{j=1}^k \kappa_j$
- $X_i = \frac{X_i^*}{\sum_{j=1}^k X_j^*} Z$

Then

- X_i : Independent, Gamma(κ_i, λ) ($i = 1, \dots, k$)
(same as X_i^*)

Note: X_i 's add up to Z

Theoretical background (continued)

Summary of the proof

To proof that X_i is independent of X_j and both are gamma distributed:

1. Take the joint pdf of the variables (all are independent gamma distributed)

$$X_i^*, X_j^*, Y^* = X_1^* + \dots + X_{i-1}^* + X_{i+1}^* + \dots + X_{j-1}^* + X_{j+1}^* + \dots + X_k^* \text{ and } Z$$

2. Use the transformations

$$X_i = \frac{X_i^*}{X_i^* + X_j^* + Y^*} Z, X_j = \frac{X_j^*}{X_i^* + X_j^* + Y^*} Z, Y = \frac{X_i^*}{X_i^* + X_j^* + Y^*} Z \text{ and}$$

$$W = X_i^* + X_j^* + Y^*$$

3. Determine the joint pdf of (X_i, X_j, Y, W)
4. Obtain that (X_i, X_j, Y, W) are independent and gamma distributed

Practical considerations

Model course

1. Get the known Z .
2. By using a sequential model determined by X_i 's, generate X_i^* 's independently of Z .
3. By using the above transformations obtain X_i 's.

Limitations

In strict sense:

- X_i : 2-parameter gamma distributed
- $E[X_i]/\text{Var}[X_i] = \text{ct}$ (independent of i)
- X_i independent of X_j

In non-strict sense (approximations):

- X_i : 3-parameter gamma distributed
- $E[X_i]/\text{Var}[X_i] \approx E[X_j]/\text{Var}[X_j]$
- $\text{Corr}[X_i, X_j]$: not too large

The sequential model

Overview

$$\begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_k \end{bmatrix} = \begin{bmatrix} \omega_{11} & 0 & \cdots & 0 \\ \omega_{21} & \omega_{22} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ \omega_{k1} & \omega_{k2} & \cdots & \omega_{kk} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \\ \vdots \\ V_k \end{bmatrix} \text{ or } \mathbf{X} = \Omega \mathbf{V} \quad (V_i \text{ independent, appr. 3-par. gamma})$$

Parameter estimation

$$\Omega \Omega^T = \text{Cov}[\mathbf{X}, \mathbf{X}] \Rightarrow \Omega \text{ by decomposition(lower triangular)}$$

$$\omega_{ii} E[V_i] = E[X_i] - \sum_{l=1}^{i-1} \omega_{il} E[V_l]$$

$$\text{Var}[V_i] = 1$$

$$\omega_{ii}^3 \mu_3[V_i] = \mu_3[X_i] - \sum_{l=1}^{i-1} \omega_{il}^3 \mu_3[V_l]$$

Link to a rainfall model

Inputs to the sequential model: $E[\mathbf{X}], \text{ Cov}[\mathbf{X}, \mathbf{X}], \mu_3[\mathbf{X}]$

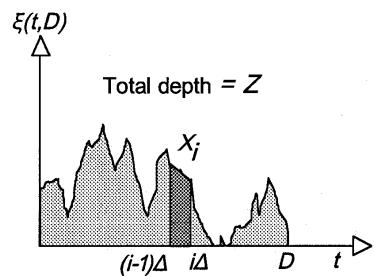
More inputs for disaggregation: $E[Z], \text{ Var}[Z], \mu_3[Z]$

Application 1 - Scaling rainfall model

General structure

$$\{\xi(t, D)\} \stackrel{d}{=} \{\lambda^{-H} \xi(\lambda t, \lambda D)\}$$

where $\xi()$: instantaneous rainfall intensity
 D : duration of the event
 t : time ($0 \leq t \leq D$)
 H : scaling exponent



$$E[\xi(t, D)] = c_1 D^H$$

$$\text{Cov}[\xi(t, D)\xi(t + \tau, D)] = (\varphi(\tau / D) - c_1^2)D^{2H}$$

$$\varphi(y) = \frac{1}{2}(c_2 + c_1^2)(1 - \beta)(2 - \beta) y^{-\beta}$$

Application 1 - Scaling rainfall model (continued)

Statistics of incremental and total depths

$$E[X_i] = c_1 \delta D^{H+1}$$

$$\text{Var}[X_i] = [(c_2 + c_1^2)\delta^{-\beta} - c_1^2]\delta^2 D^{2(H+1)}$$

$$\text{Cov}[X_i, X_j] = [(c_2 + c_1^2)\delta^{-\beta} f(|j - i|, \beta) - c_1^2]\delta^2 D^{2(H+1)}$$

$$E[Z] = c_1 D^{H+1}$$

$$\text{Var}[Z] = c_2 D^{2(H+1)}$$

where

$$\delta = \Delta / D$$

$$f(m, \beta) = \frac{1}{2}[(m-1)^{2-\beta} + (m+1)^{2-\beta}] - m^{2-\beta}, \quad m > 0$$

Parameters

c_1 (= 1.05): mean value parameter

c_2 (= 0.44): variance parameter

β (= 0.32): correlation decay parameter

H (= -0.20): scaling exponent

Application 2 - ARMA(1,1) model

General structure

Stationary model, Markovian in continuous time: $\text{Cov}[\xi(t), \xi(t + \tau)] = k_2 e^{-\beta_2 \tau}$

Statistics of incremental and total depths

$$\mathbb{E}[X_i] = c_1 \Delta$$

$$\text{Var}[X_i] = 2(k_2^2 / \beta_2^2)(\beta_2 \Delta - 1 + e^{-\beta_2 \Delta})$$

$$\text{Cov}[X_i, X_j] = 2(k_2^2 / \beta_2^2)(1 - e^{-\beta_2 \Delta})^2 e^{-\beta_2(|j-i|-1)\Delta}$$

$$\mathbb{E}[Z] = c_1 D$$

$$\text{Var}[Z] = 2(k_2^2 / \beta_2^2)(\beta_2 D - 1 + e^{-\beta_2 D})$$

Parameters

c_1 (=0.65): mean value parameter

k_2 (=1.25): variance parameter

β_2 (=1.58): correlation decay parameter

Application 3 - AR(1) model

General structure

Stationary model, Markovian in discrete time: $\text{Cov}[X_i, X_j] = C \rho^{|i-j|}$

Parameters = statistics of incremental depths

$E[X_i]$: (=0.577) mean of incremental depth (for $D = 1$ h)

$C = \text{Var}[X_i]$ (=0.776) variance of incremental depth (for $D = 1$ h)

ρ (=0.53) first autocorrelation coefficient

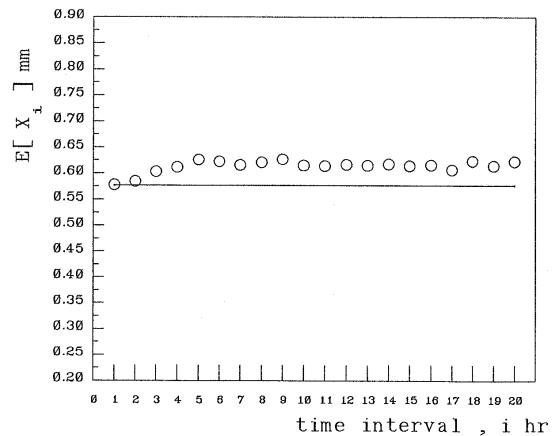
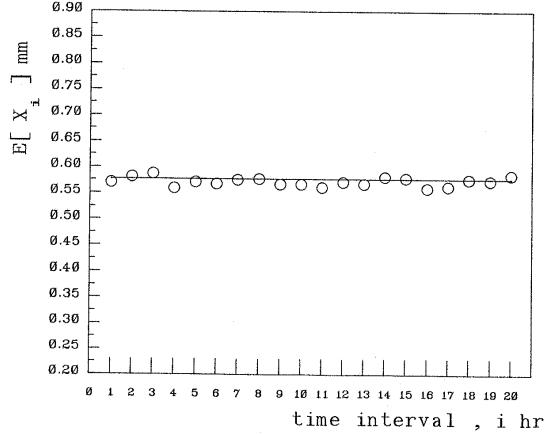
Statistics of total depth

$$\mathbb{E}[Z] = k \mathbb{E}[X_i]$$

$$\text{Var}[Z] = \sum_{i=1}^k \sum_{j=1}^k \text{Cov}[X_i, X_j]$$

Simulation results - Application 1 - Scaling

Mean values (Disaggregation and sequential model)

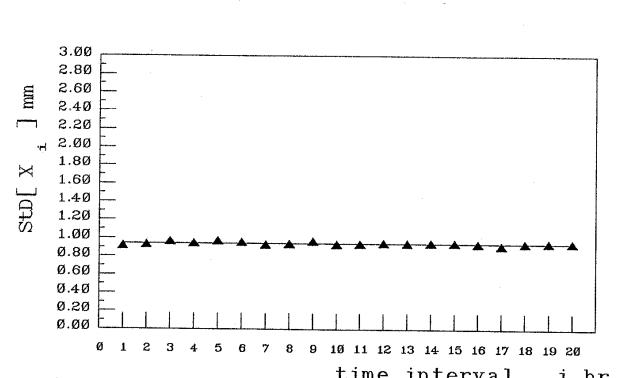
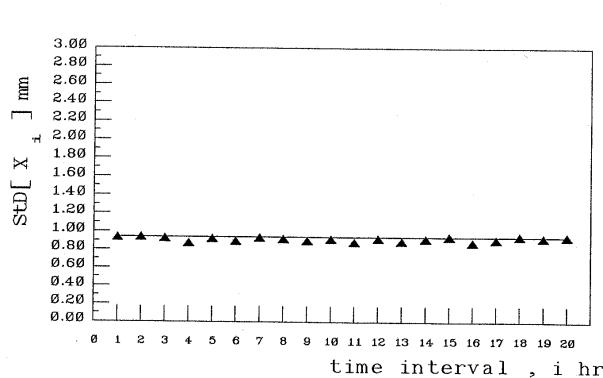


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Simulation results - Application 1 - Scaling

Standard deviations (Disaggregation and sequential model)

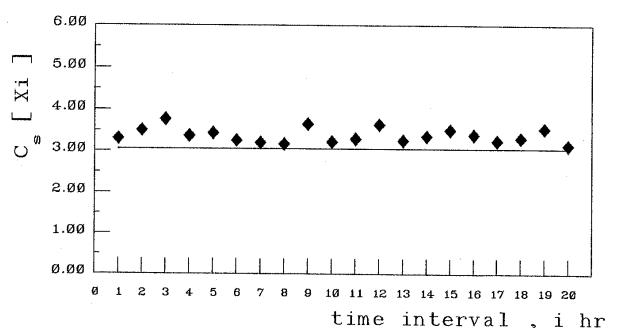
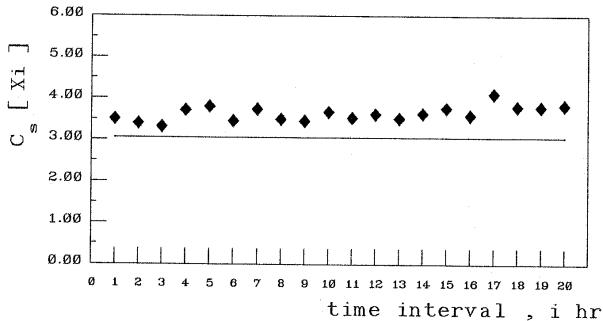


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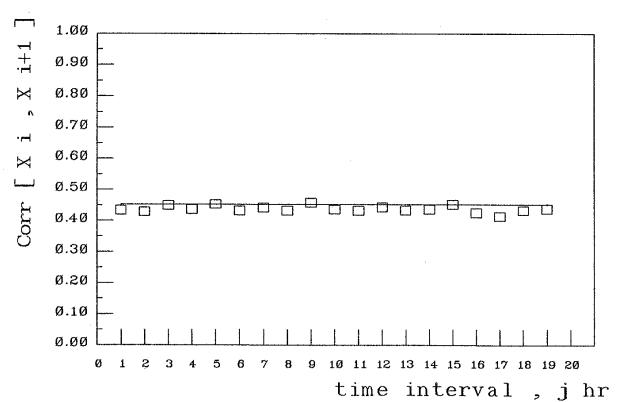
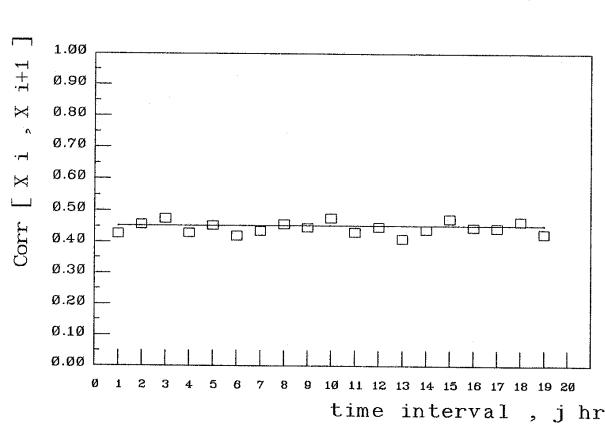
Simulation results - Application 1 - Scaling

Skewness coefficients (Disaggregation and sequential model)



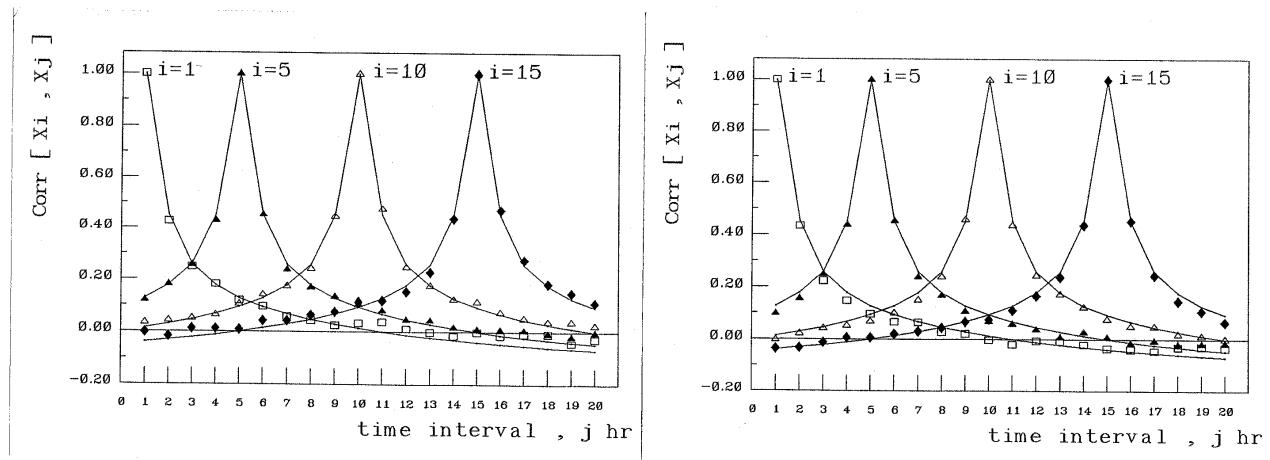
Simulation results - Application 1 - Scaling

First autocorrelation coefficients (Disaggregation and sequential model)



Simulation results - Application 1 - Scaling

Autocorrelation coefficients (Disaggregation and sequential model)

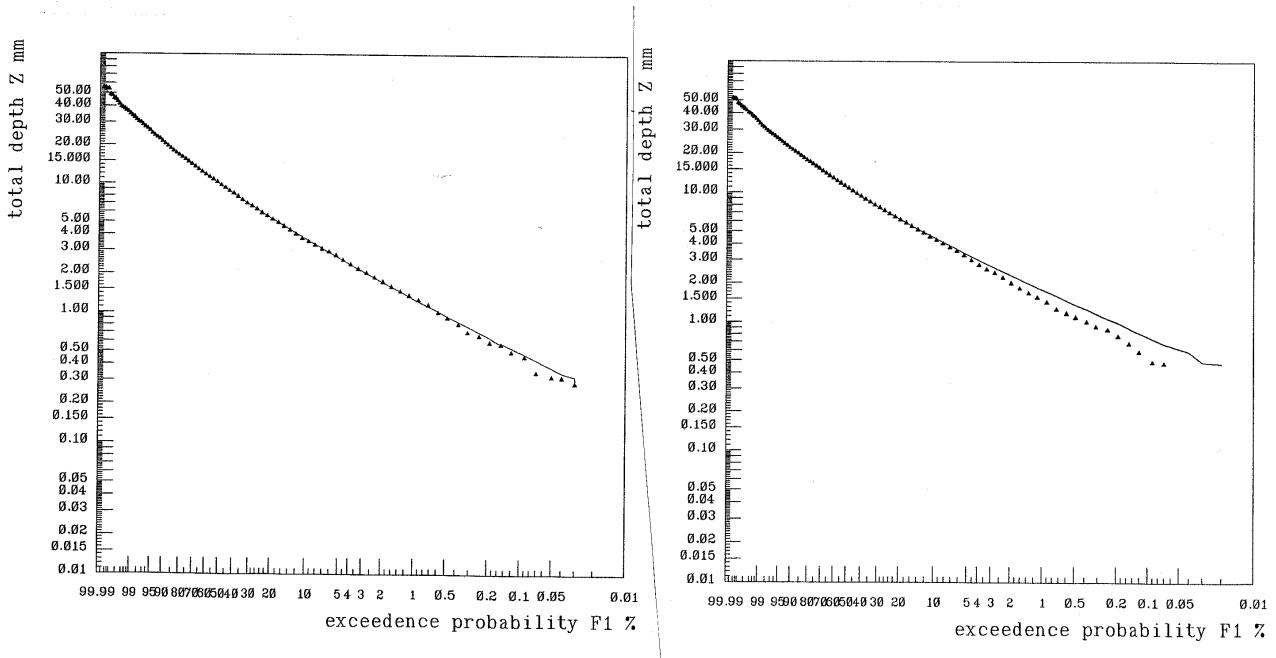


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Simulation results - Application 1 - Scaling

Distribution function of Z (Disaggregation and sequential model)

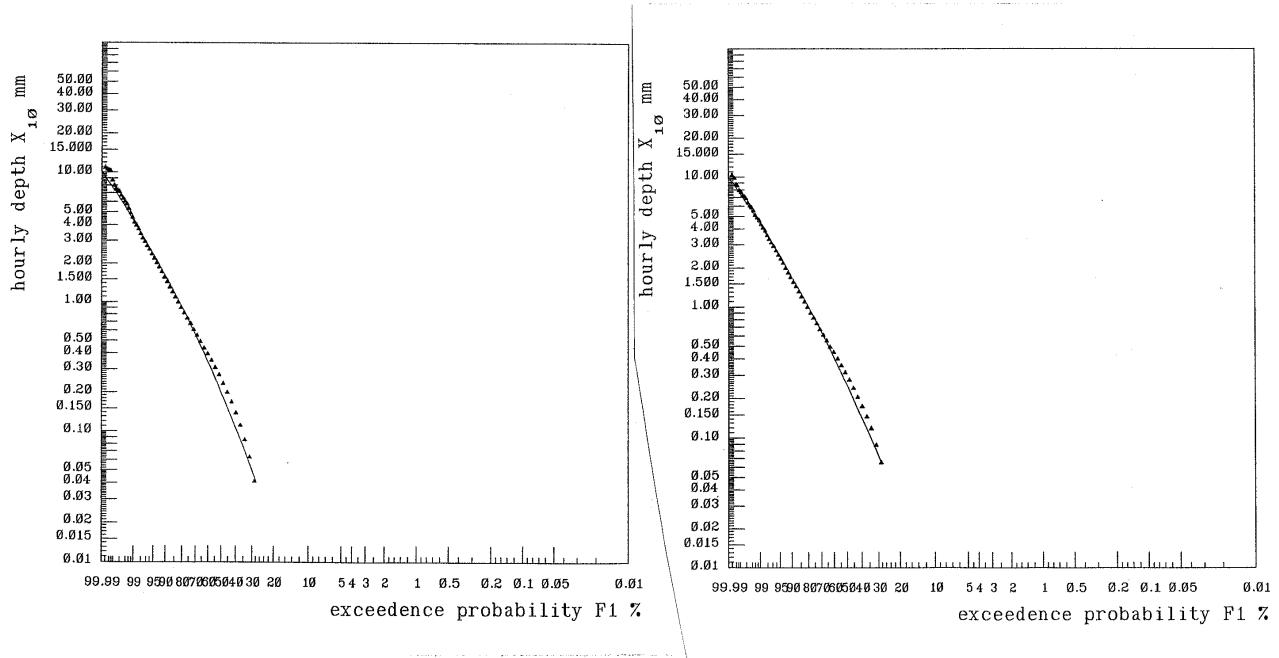


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Simulation results - Application 1 - Scaling

Distribution function of X_{10} (Disaggregation and sequential model)

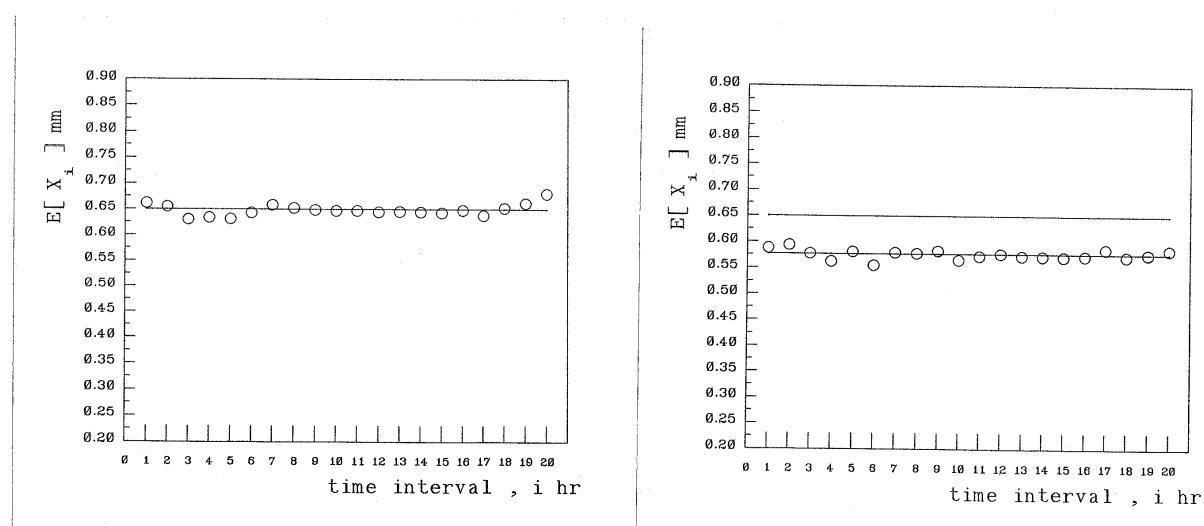


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Simulation results - Application 2 - ARMA(1,1)

Mean values (Consistent and inconsistent case)

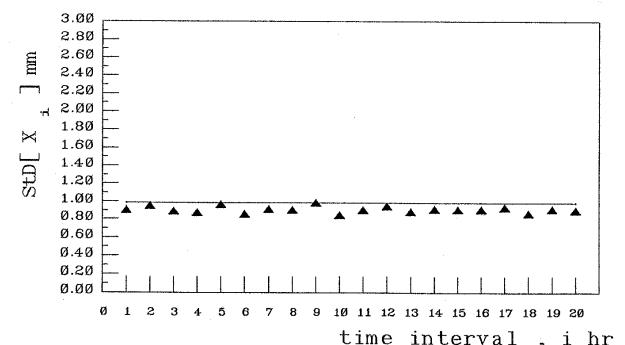
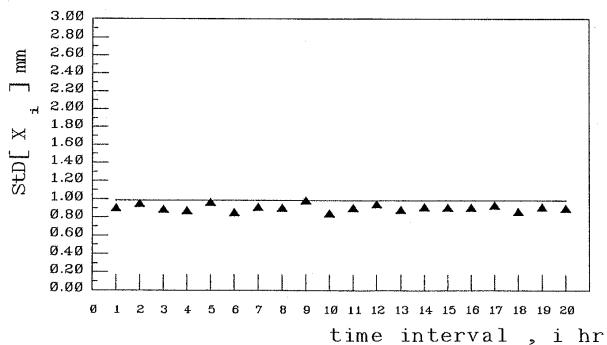


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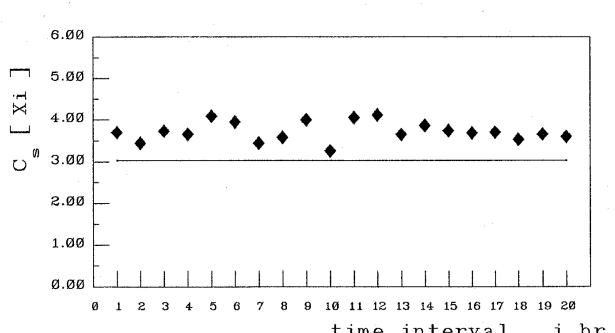
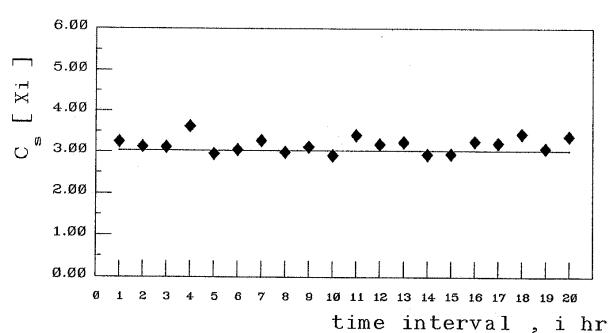
Simulation results - Application 2 - ARMA(1,1)

Standard deviations (Consistent and inconsistent case)



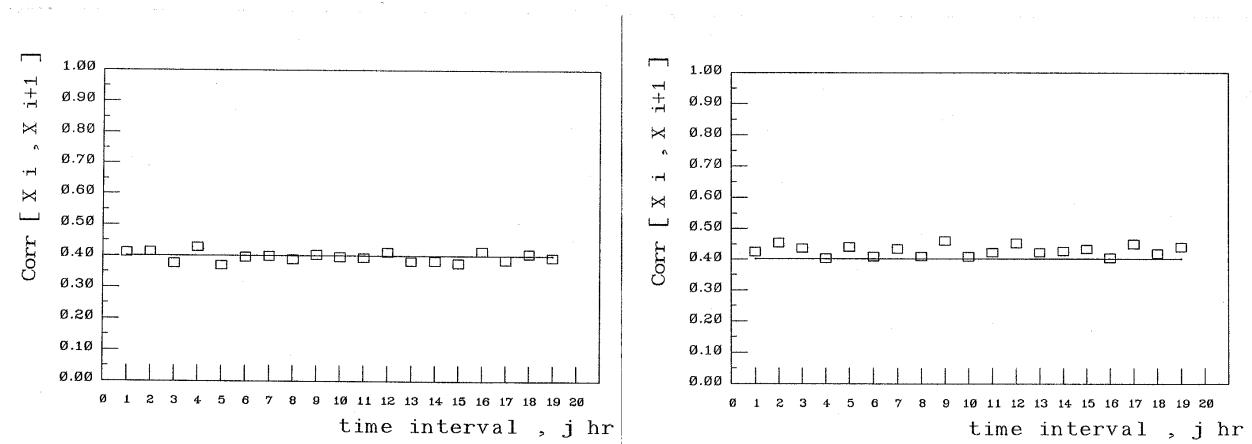
Simulation results - Application 2 - ARMA(1,1)

Skewness coefficients (Consistent and inconsistent case)



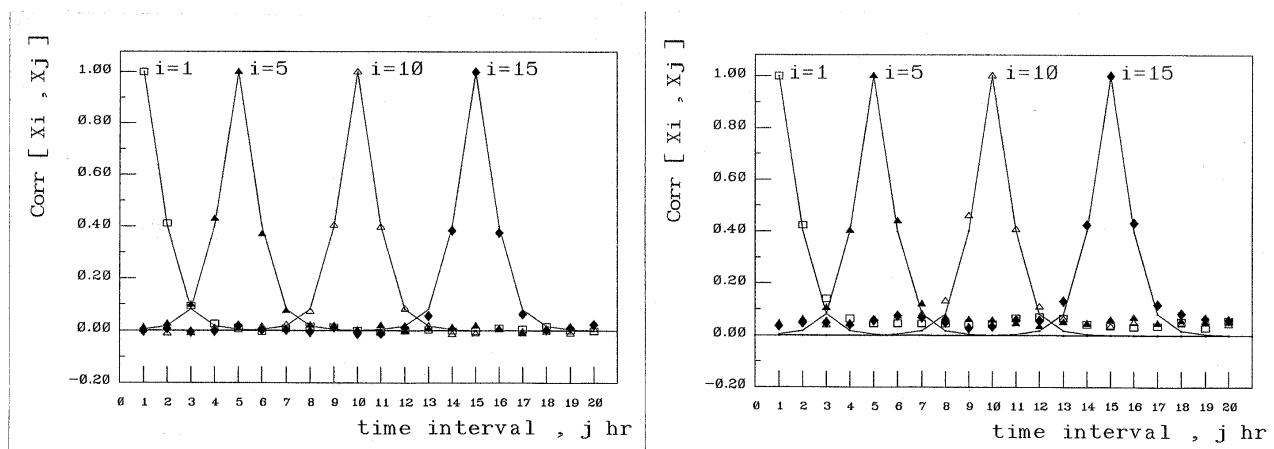
Simulation results - Application 2 - ARMA(1,1)

First autocorrelation coefficients (Consistent and inconsistent case)



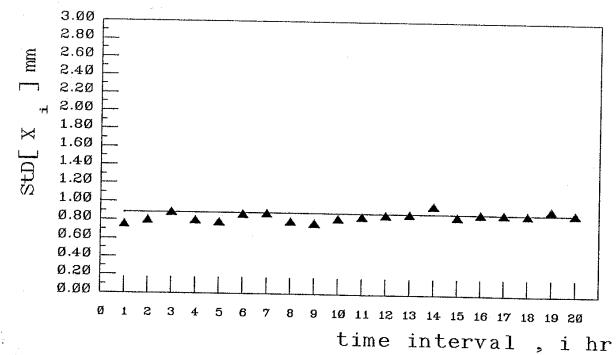
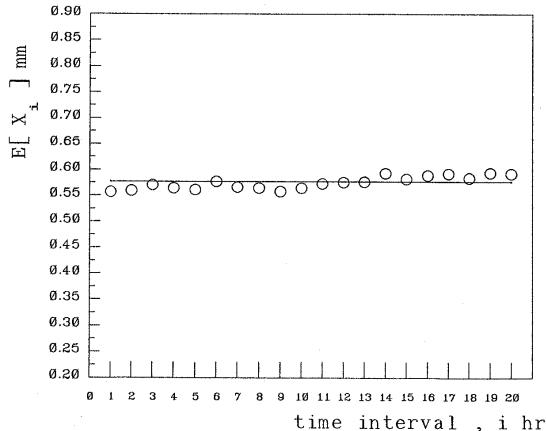
Simulation results - Application 2 - ARMA(1,1)

Autocorrelation coefficients (Consistent and inconsistent case)



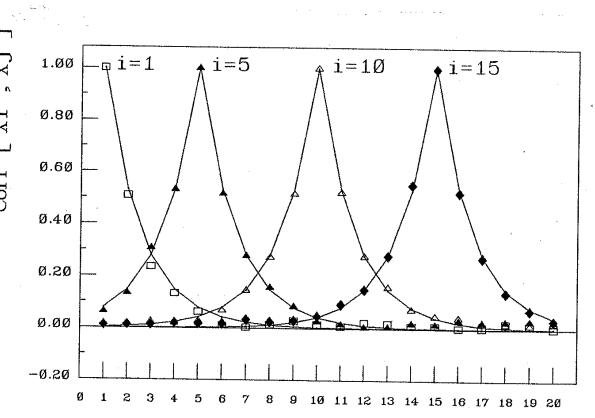
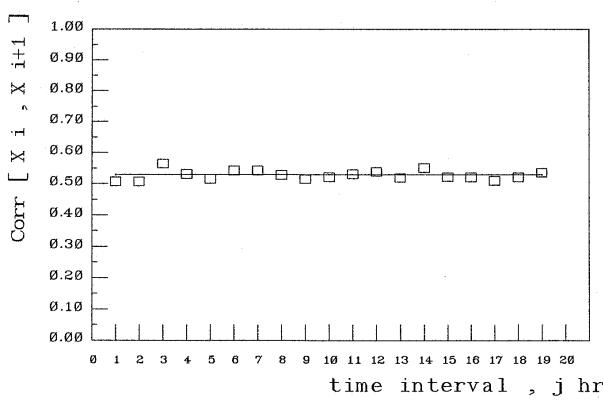
Simulation results - Application 3 - AR(1)

Mean values and Standard deviations



Simulation results - Application 3 - AR(1)

Autocorrelation coefficients



Simulation results - Application 1 - Scaling

Dimensionless mass curves

